



UNIVERSITATEA DIN  
BUCUREȘTI  
VIRTUTE ET SAPIENTIA



# Satellite Mega-constellations: operational risks and the impact on ground-based astronomical observations

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PhD Supervisor  
Professor Mirel BÎRLAN

# Presentation Structure

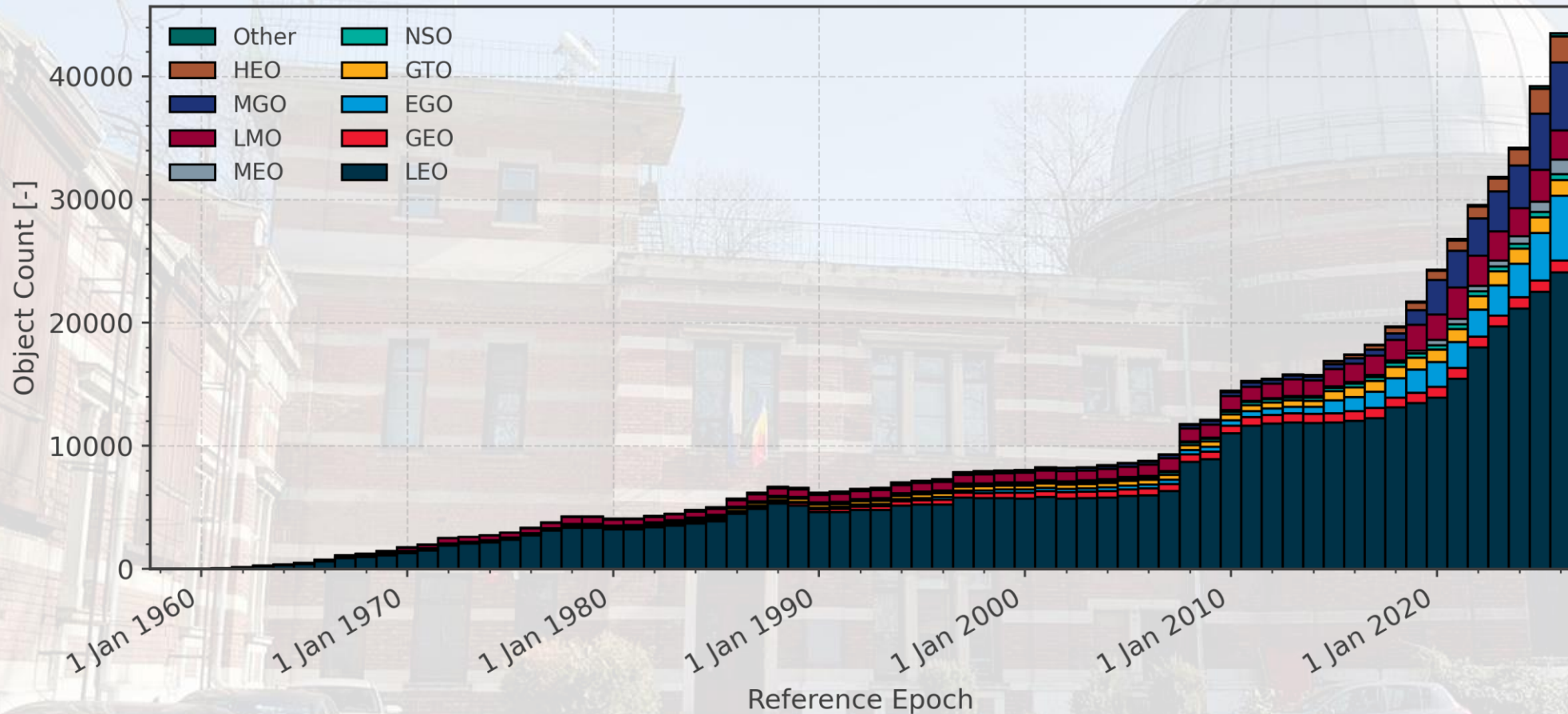
Section	Content	Page range
Introduction	scope of the thesis	2 - 3
Theoretical background	current situation in LEO orbits	4 - 9
Identified issues	<ul style="list-style-type: none"> <li>○ increase in operational risk</li> <li>○ the impact on ground-based astronomy</li> </ul>	10
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Results	case studies, data, figures	16 - 32
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# Scope of the Thesis

- ❑ the study of artificial near-Earth objects in the context of satellite constellations
- ❑ the impact on ground-based astronomical observations

# Chapter 1: The Mega-Constellation Paradigm

Count evolution by object orbit



Credit: ESA (Annual Report 2025)

**Forecast:** approximately 100,000 satellites will be deployed into LEO orbits by the end of 2030 (Boley and Byers, 2021)

11 : total number of constellations

11,582 : total number of launched satellites

9,201 : total number of operational satellites

**1,896,629 : total number of satellites for which  
deployment licenses into LEO orbits have been requested**

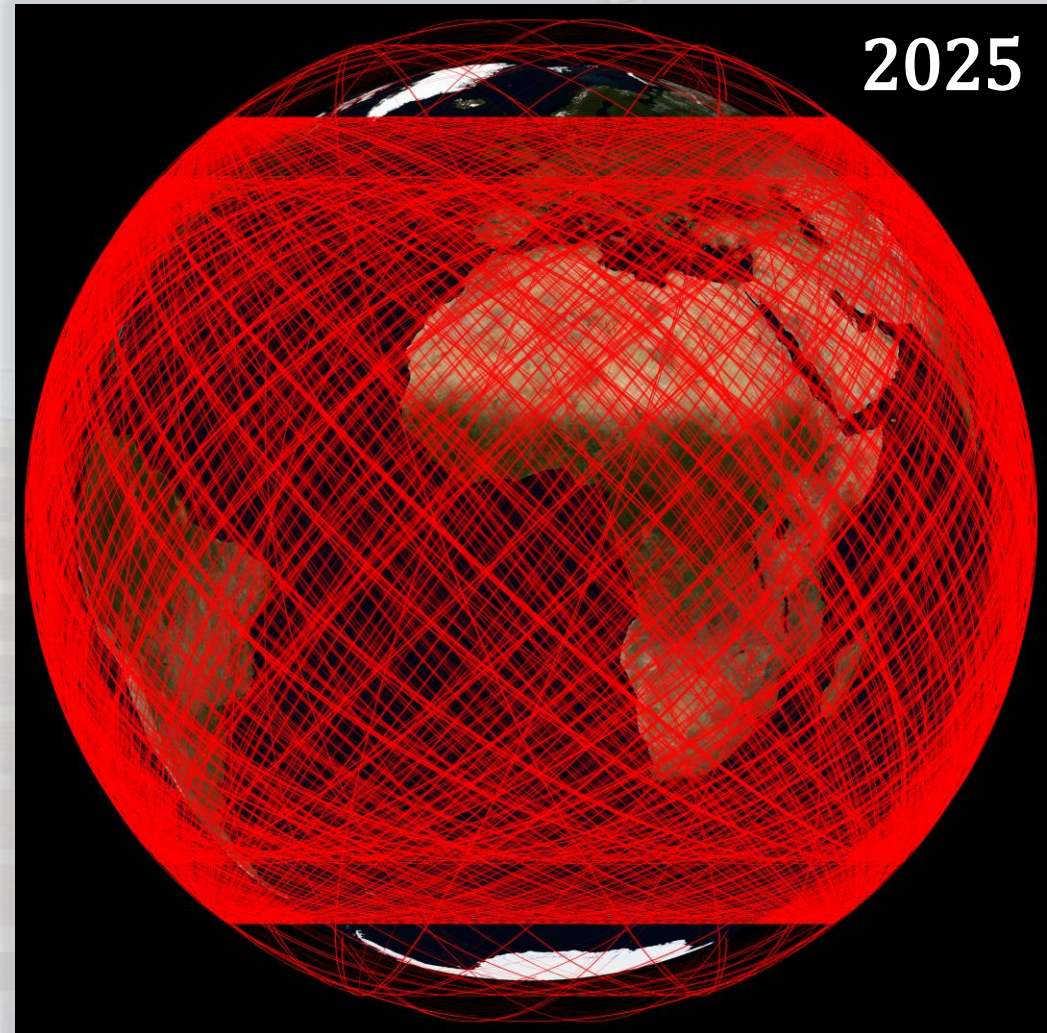
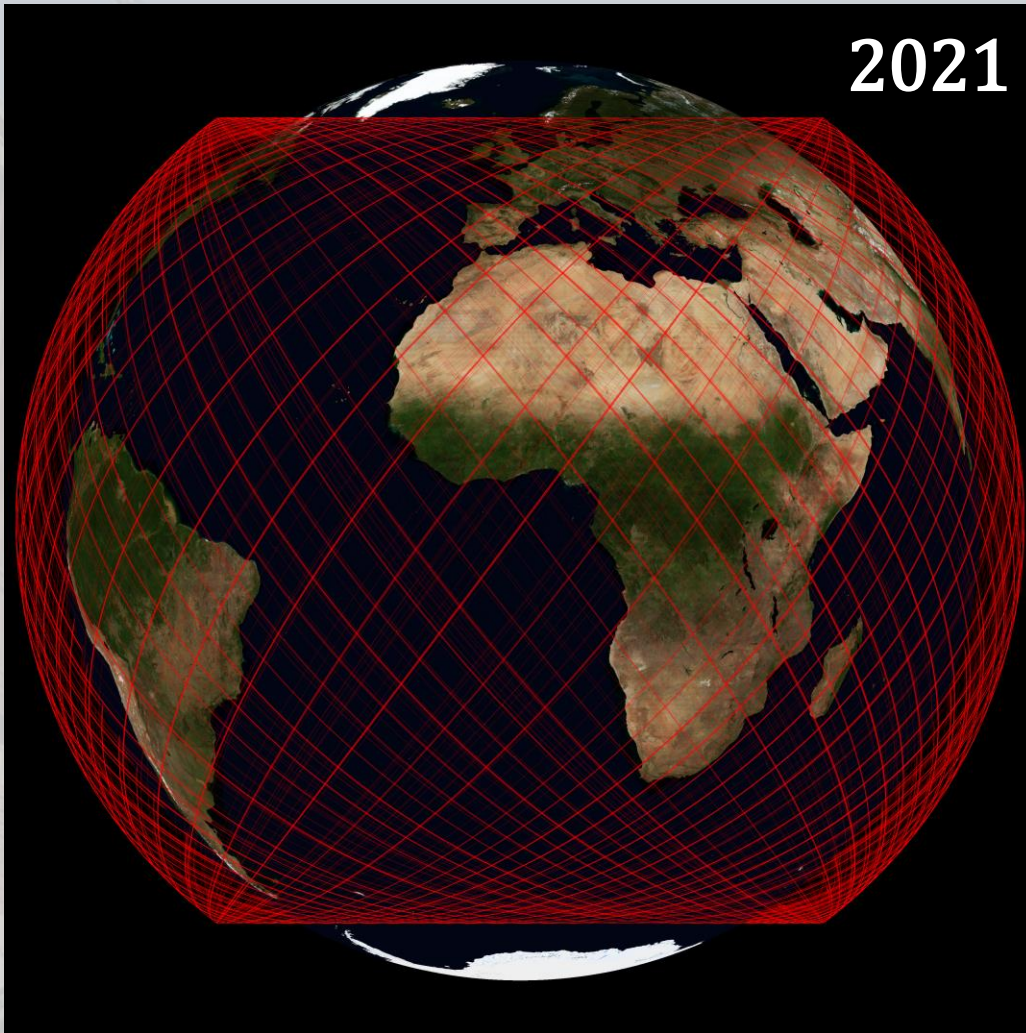
**→ 246% annual growth**



*Credit: Jonathan McDowell, <https://planet4589.org>, (March 2026)* 5

# Orbital Density of the Starlink Mega-Constellation

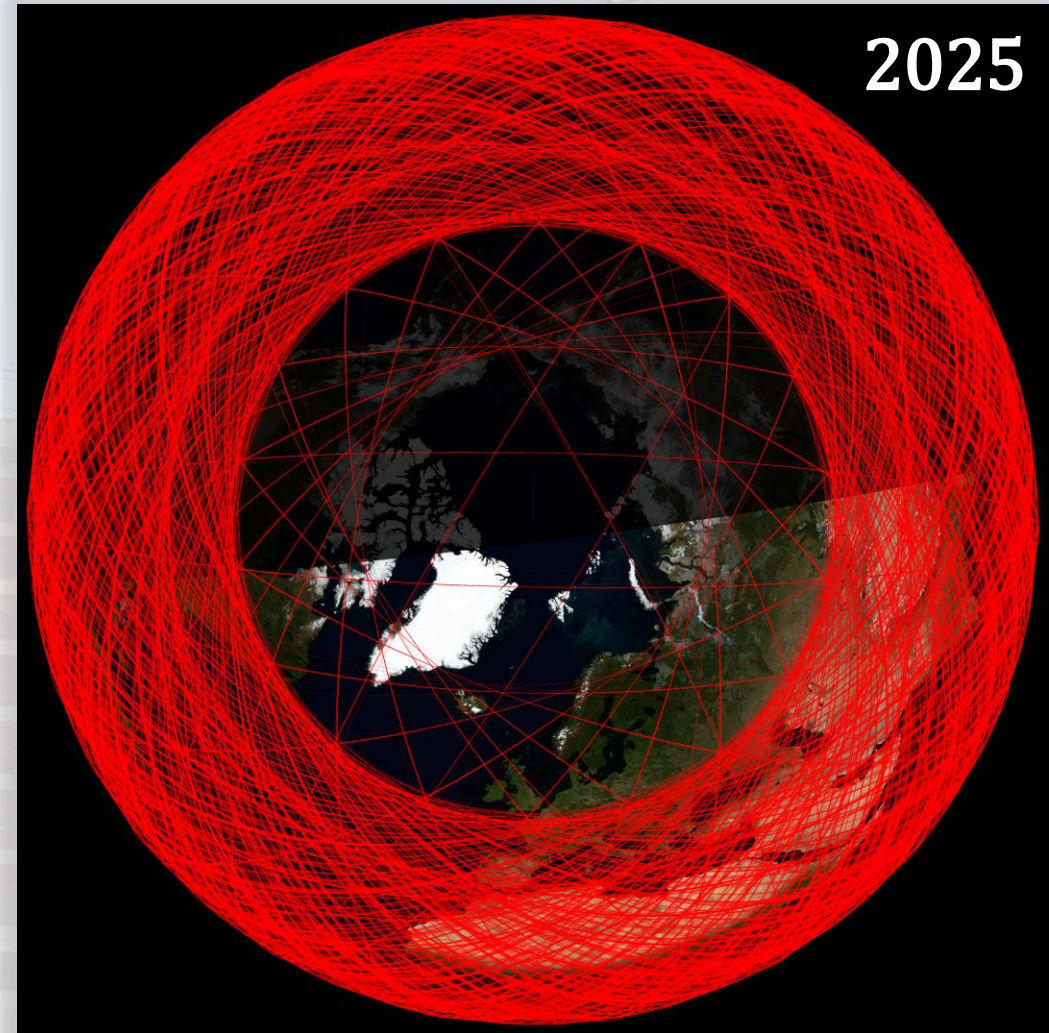
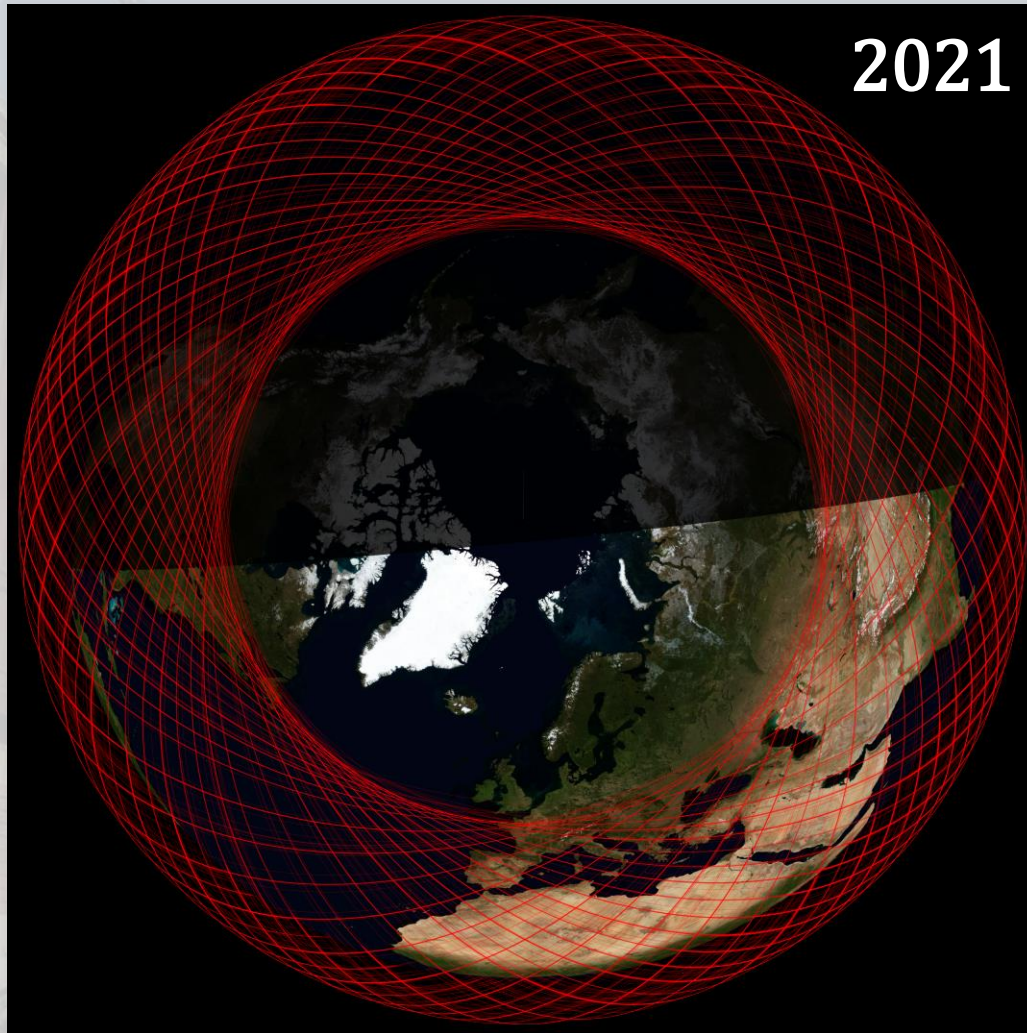
EQ view



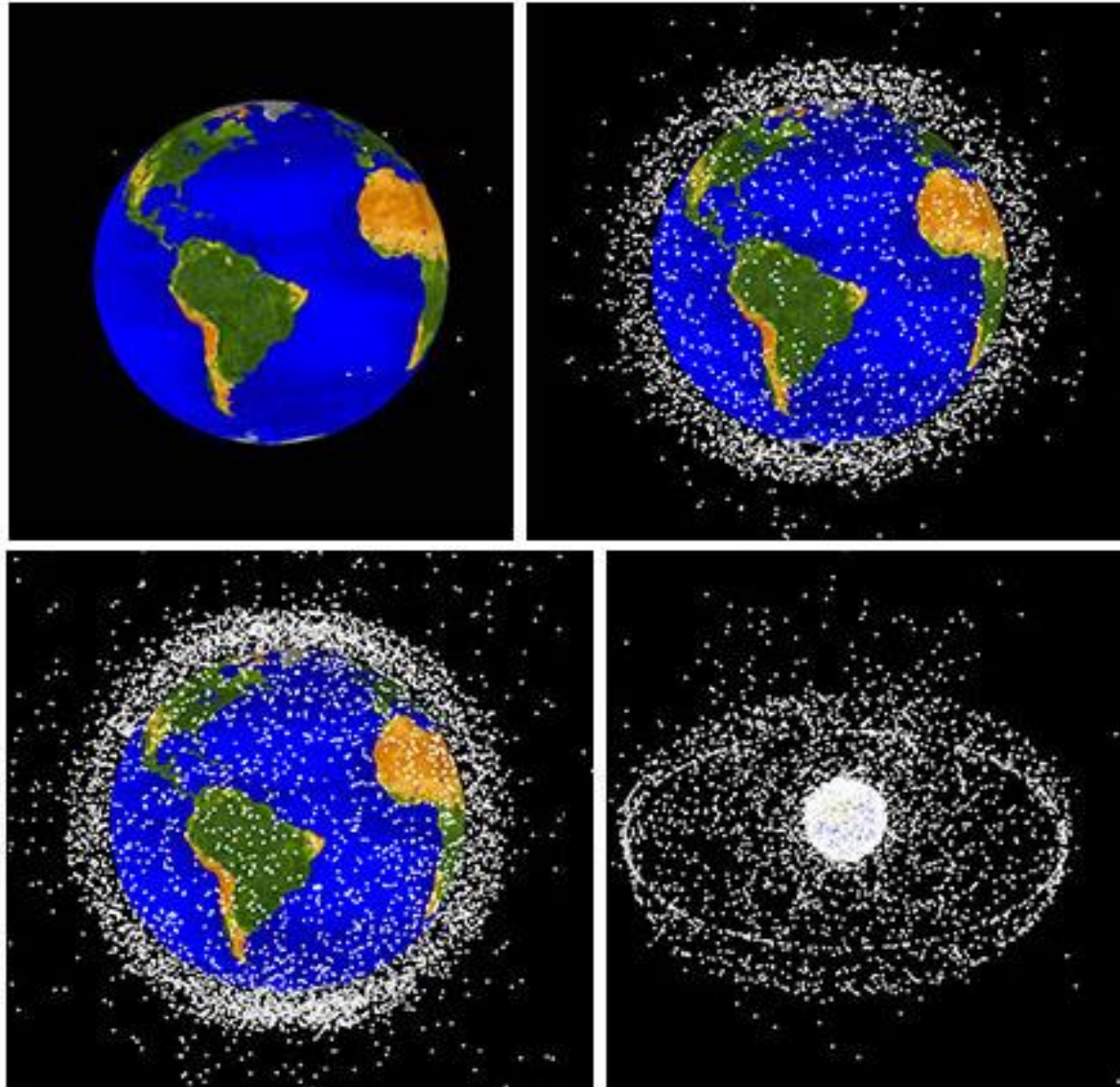
*Simulation: Astronomical Institute of the Romanian Academy (AIRA)*

# Orbital Density of the Starlink Mega-Constellation

Polar view



*Simulation: Astronomical Institute of the Romanian Academy (AIRA)*



*Credit: ESA*

# Kessler Syndrome

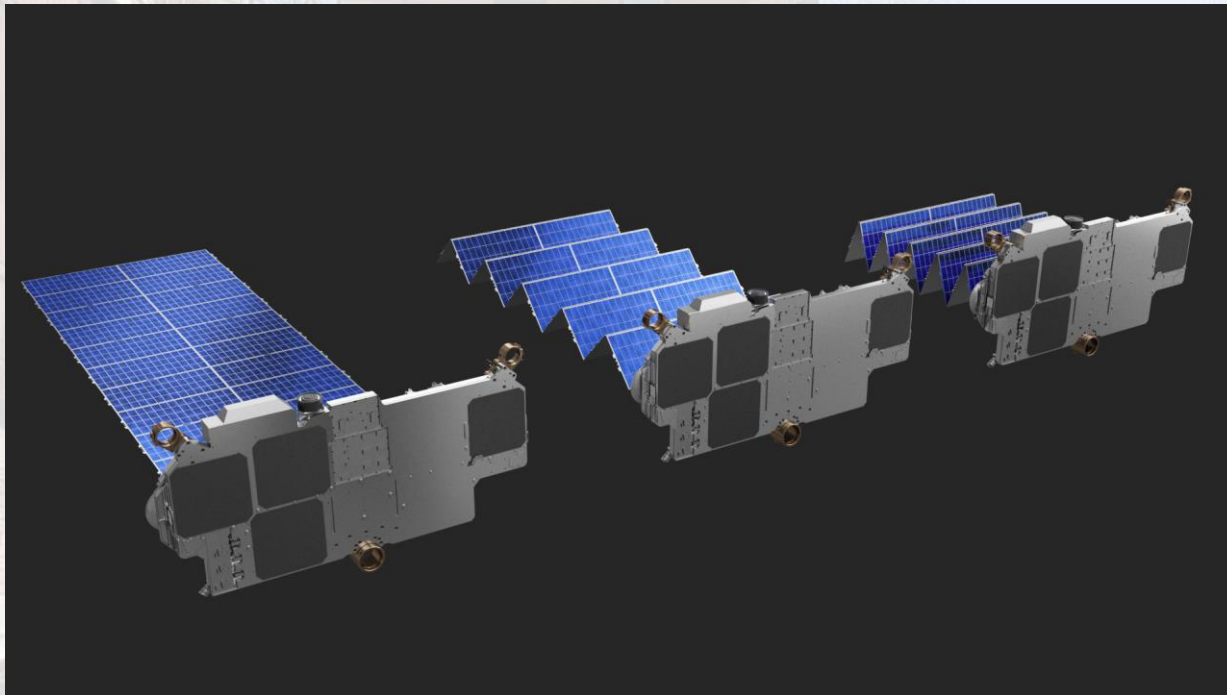
- the saturation of Low Earth Orbits (LEO) with satellites and space debris
- the exponential increase in the number of collisions between objects
- a self-sustaining collisional cascade, capable of isolating Earth for extended periods of time

*(Kessler and Cour-Palais, 1978)*

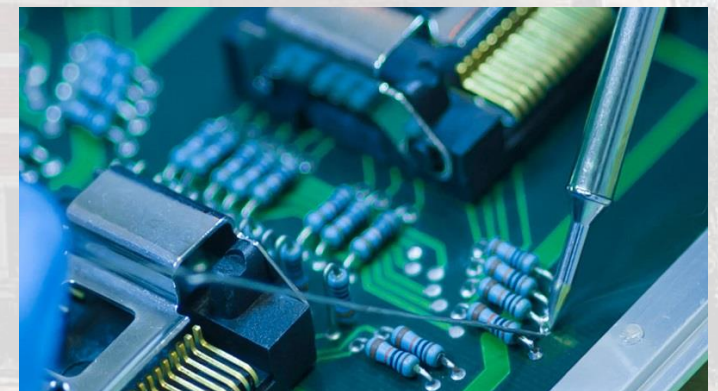
# Key Technological Enablers

Miniaturization, the adoption of COTS components, and Reusable Launch Vehicles (RLVs) have led to:

- reduction in satellite size, mass, and power consumption (SWaP)
- faster access to advanced commercial technologies
- increased economic feasibility of satellite constellations



Credit: [www.cgtrader.com](http://www.cgtrader.com) / [www.gdca.com](http://www.gdca.com)



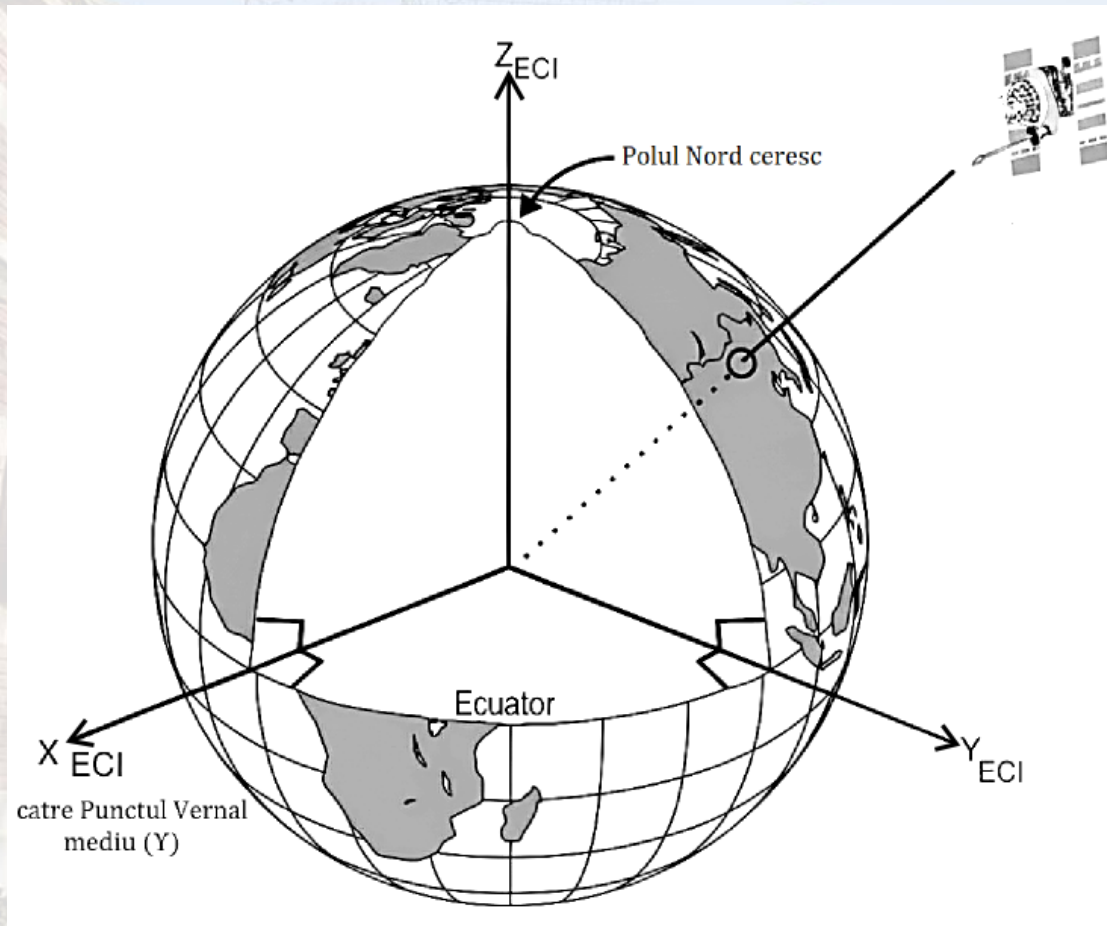
# Chapter 2: Operational Risks in Low Earth Orbit (LEO)

Operational Risk	Main Effect
Collision and Fragmentation	collisions, fragmentations, and the increasing density of orbital debris
Radiation Environment	degradation of electronic components and the onset of functional anomalies
Electromagnetic Interference (EMI)	disruption of satellite communications, navigation, and control
Orbital Decay and Attitude Control Degradation	reduction in orbital altitude and compromised mission stability

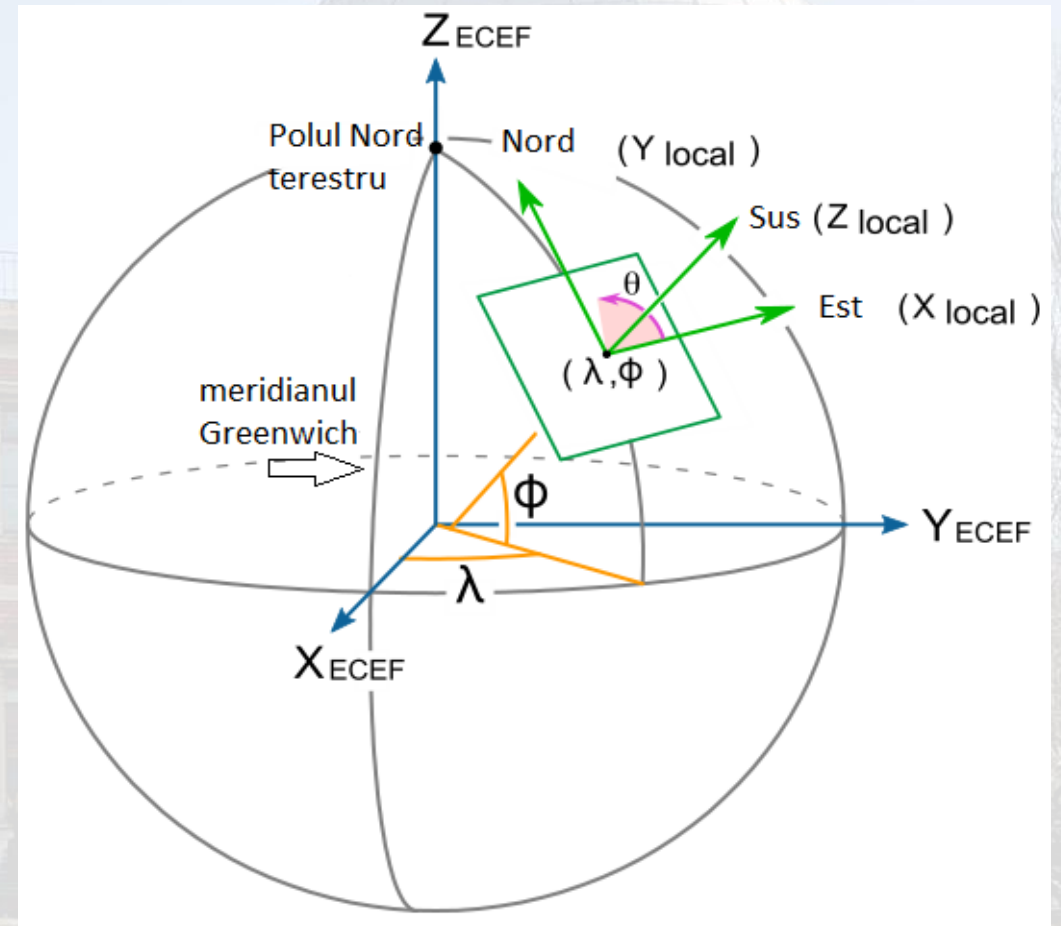


# Chapter 3: Applied Orbital Mechanics in LEO

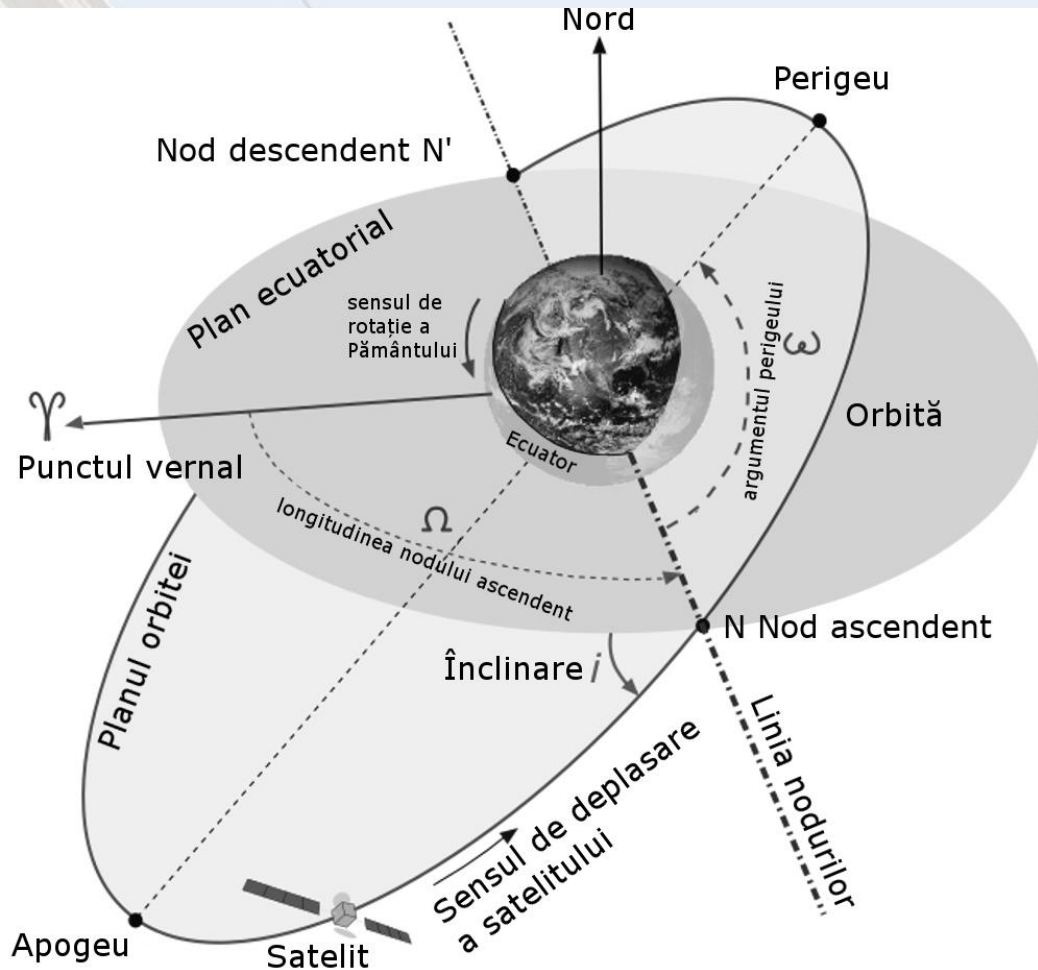
*ECI – Earth Centered Inertial*



*ECEF - Earth-Centered Earth-Fixed*



# Classical Keplerian Elements (COE)



## I. Shape and Size Parameters (2 elements: $a$ and $e$ )

**Semi-major axis ( $a$ )** – orbital size

**Eccentricity ( $e$ )** – orbital shape

## II. Orbital Orientation Parameters (3 elements: $i$ , $\Omega$ and $\omega$ )

**Inclination ( $i$ )** – angle with respect to the equatorial plane

**Longitude of the Ascending Node ( $\Omega$  or RAAN)** – orientation of the orbital plane with respect to the vernal equinox

**Argument of Perigee ( $\omega$ )** – position of perigee with respect to the ascending node

## III. Position Parameter (1 element: $M$ )

**Mean Anomaly ( $M$ )** – an angle that evolves linearly in time and describes the position of the satellite along its orbit

# Dominant Orbital Perturbations in LEO

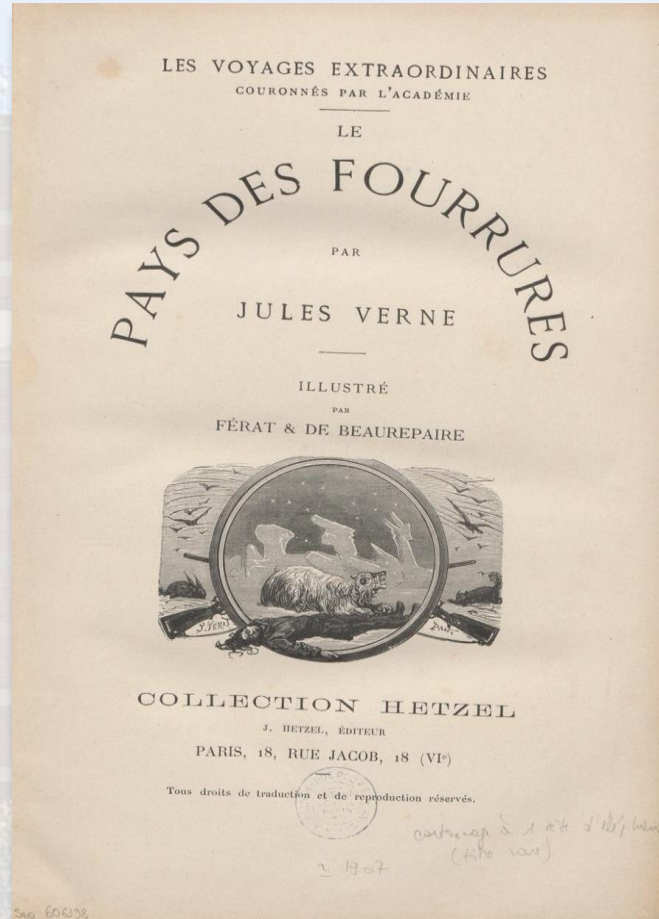
Perturbation	Effect	Consequence
$J_2$ - Earth's polar flattening (oblateness)	orbital plane precession	secular variations: nodal precession, apsidal precession
Atmospheric Drag	reduces and circularizes the orbit	orbital decay, followed by reentry

$$\vec{a}_{\text{tot}} = \underbrace{-\frac{\mu}{r^3}\vec{r}}_{\text{2-body}} + \underbrace{\vec{a}_{\text{drag}} + \vec{a}_{J_2}}_{\text{perturbații dominante LEO}}$$

# Chapter 4: Physics of Atmospheric Reentry

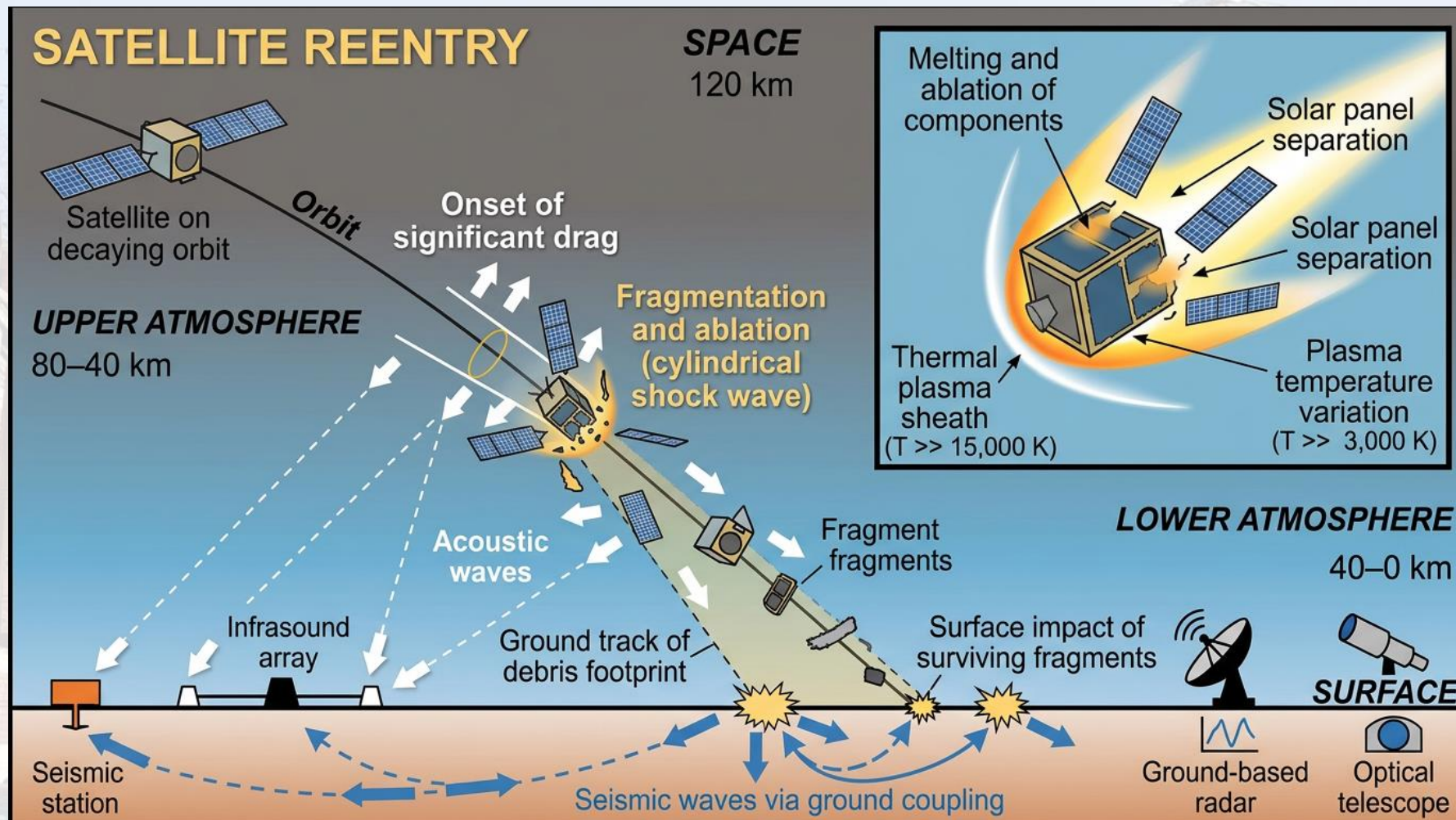
Jules Verne, *Le Pays des fourrures* (1873):

- *"The sun, at its culmination, was completely obscured, and Lieutenant Hobson could no longer calculate the position of the island."*
- *"Without Sun, Moon, or stars, the instruments become useless, and the true position of the island cannot be determined."*
- Astronomer Thomas Black refuses to believe that the ephemerides are wrong: *"it is no longer where they think it is"*

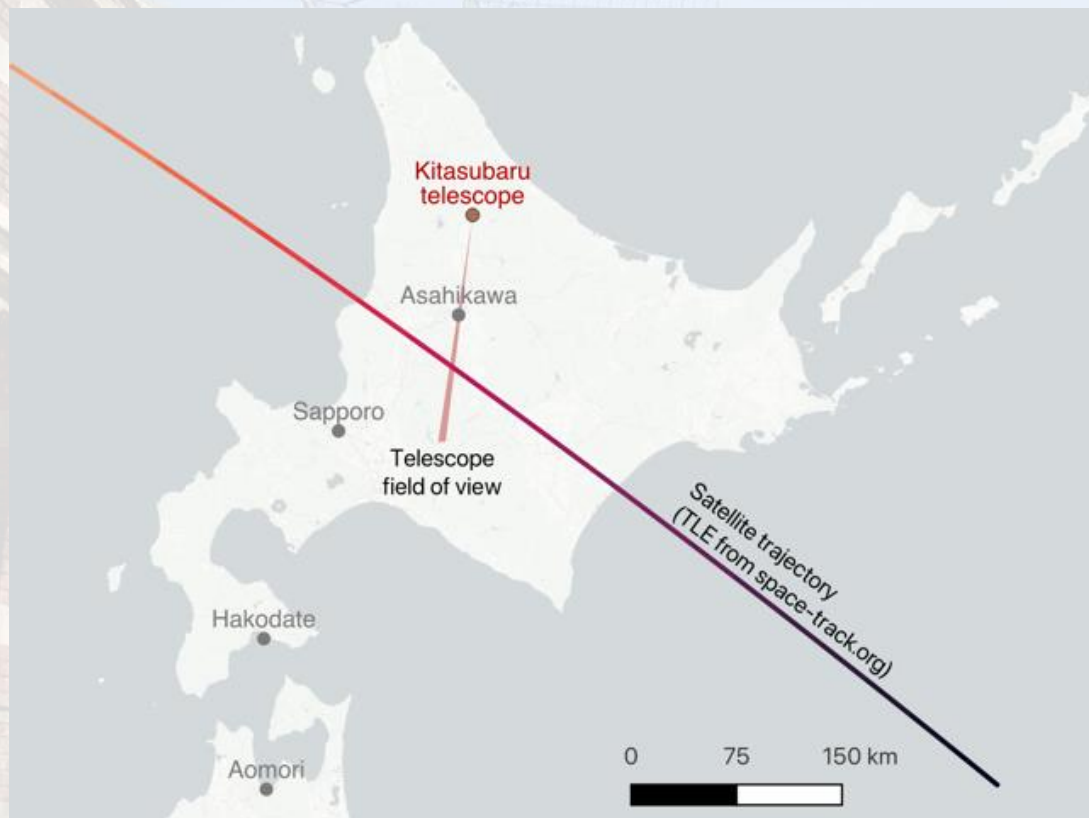


Analogy:

- a passive object (iceberg ↔ orbital debris) in a dynamic environment (ocean currents ↔ atmosphere), whose position is estimated through periodic observations
- the prediction of the event (total eclipse ↔ reentry) is accurate, but the position of the observer/object is affected by significant uncertainty
- the physical models are accurate, but the position remains constrained by environmental uncertainties: atmospheric density, aerodynamic drag, perturbations



# I. Controlled Reentry of Starlink-1353



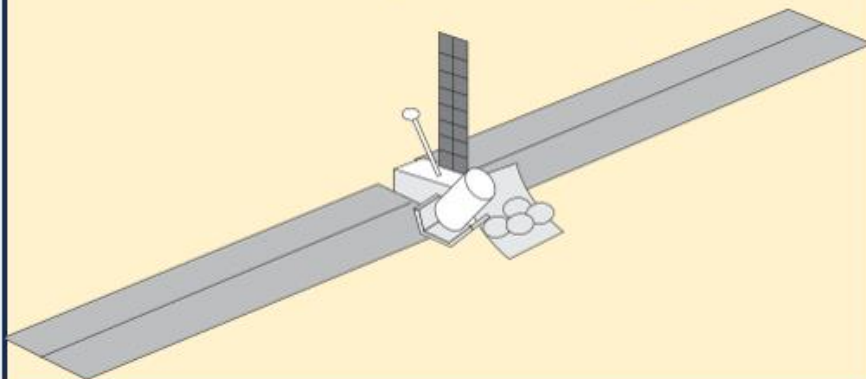
## Event Timeline:

- first-generation satellite
- launched on 22 April 2020, but anomalies occurred during orbital insertion
- on 9 June 2020, it was declared non-functional by the operator SpaceX
- following deorbit maneuvers, on 21 February 2023 the satellite reentered the atmosphere
- the descent phase was captured by a telescope at the Kitasubaru Astronomical Observatory (Japan)

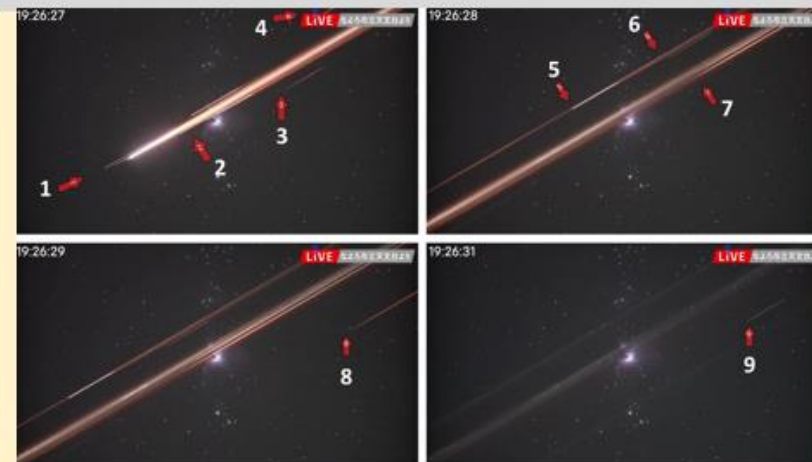


## Aim

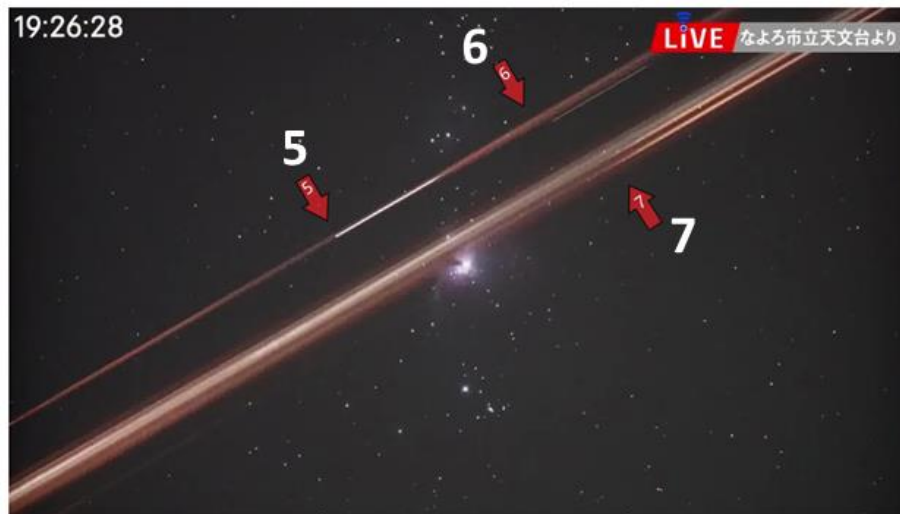
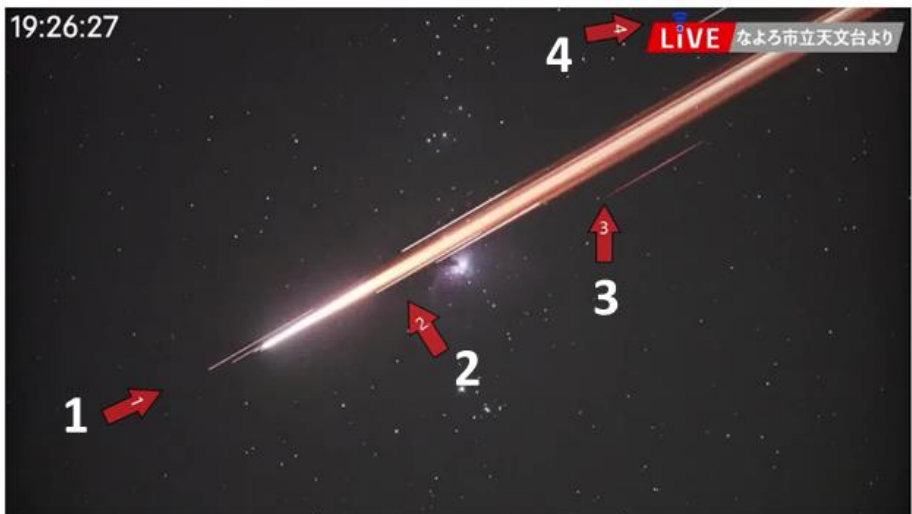
- hypothesis about the shape of the Starlink-1353 satellite and the mass distribution of the internal components
- approximation of the number of fragments, composition and their mass upon re-entry phase



## Methods



- visual frame by frame analysis
- simulations with DAS for plausible and non-plausible scenarios
- dynamical behaviour before the moment of planned re-entry



## Frame-by-frame analysis

15 fragments were identified following the breakup of the main body:

- arrow 1 => 4 fragments
- arrow 2 => 3 fragments
- arrow 3 => 1 fragment
- arrow 4 => 1 fragment
- arrow 5 => 1 fragment
- arrow 6 => 1 fragment
- arrow 7 => 2 fragments
- arrow 8 => 1 fragment
- arrow 9 => 1 fragment

## Estimation of the mass distribution of the Starlink-1353 satellite components

Generic component	Number of items	Generic materials	Min. - Max. mass per unit [kg]	Probability of hitting Earth	Potential residuals
Solar panel	1	aluminium alloy silicium	70 - 100	0	alumina
Satellite body	1	aluminum alloy	90 - 130	0	alumina
Thruster internals	1	iron	3 - 1.5	high	iron
Ion thruster	1	aluminum alloy graphite tungsten/ tantali	7 - 2.5	high	alumina graphite tungsten/ tantali
Reaction wheel	4	stainless steel	1 - 0.25	high	stainless steel
Comms. components	4	silicon carbide	1 - 0.25	high	silicon carbide
Comms. antenna	2	aluminium alloy	1 - 0.25	low	alumina
Li-Ion batteries	4	aluminium alloy silicium / iron	18 - 5	high	alumina iron
Onboard electronics	1	aluminum alloy FR4 / tantali silicium / tungsten	3 - 1.5	medium	alumina tantali tungsten
Stacking racks	3	Inconel	1 - 0.33	medium	stainless steel/ alumina
Fastening systems	1	Inconel	1 - 0.5	medium	stainless steel/ alumina
Cables	1	cooper alloy aluminium alloy	1 - 0.5	0	alumina

## Plausible Scenario

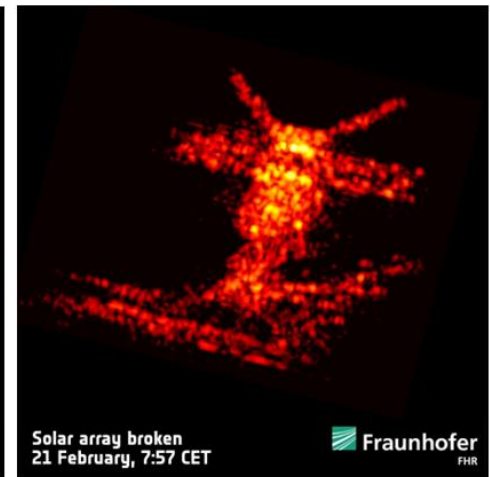
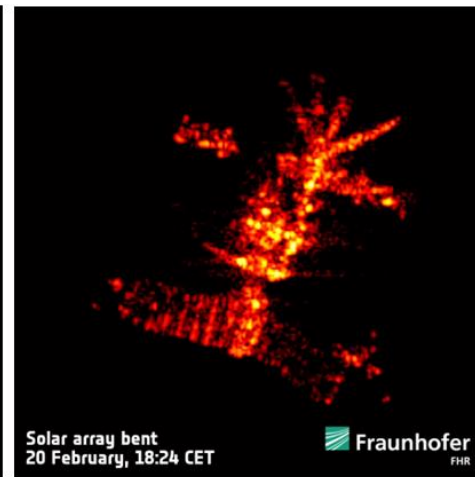
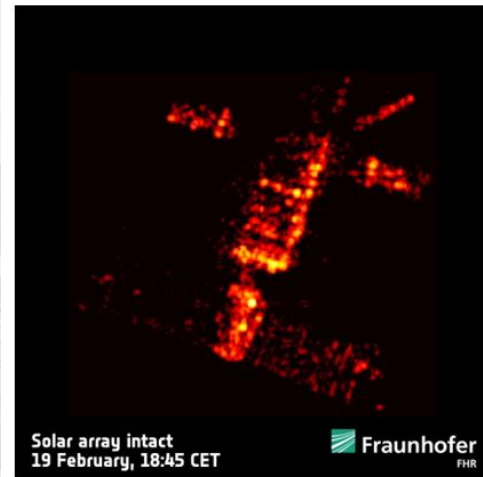
Generic component	Number of items	Generic material	Demise Alt [km]	Total DCA [sq m]
Root Object	1	Aluminum (generic)	0	15.12
Solar panel	1	Aluminum (generic)	14.5	0
Satellite body	1	Aluminum (generic)	64.4	0
Thruster internals	1	Iron	0	0.38
Reaction wheel	4	Stainless Steel (generic)	0	2.38
Comms comp	4	Silicon Carbide	0	1.98
Comms antenna	2	Aluminum (generic)	0	2.18
Li-ion batteries	4	Aluminum (generic)	0	4.4
OnBoard electronics	1	Aluminum (generic)	0	0.99
Ion thruster	1	Tungsten	0	0.6
Stacking racks	3	Inconel 600	0	1.79
Fastening systems	1	Inconel 600	0	0.43
Cables	1	Copper Alloy	50.9	0

## Non-Plausible Scenario

Generic component	Number of items	Generic material	Demise Alt [km]	Total DCA [sq m]
Root Object	1	Aluminum (generic)	0	9.62
Solar panel	1	Aluminum (generic)	0	0.52
Satellite body	1	Aluminum (generic)	0	9.1
Thruster internals	1	Iron	0	0
Reaction wheel	4	Stainless Steel (generic)	0	0
Comms comp	4	Silicon Carbide	0	0
Comms antenna	2	Aluminum (generic)	0	0
Li-ion batteries	4	Aluminum (generic)	0	0
OnBoard electronics	1	Aluminum (generic)	0	0
Ion thruster	1	Tungsten	0	0
Stacking racks	3	Inconel 600	0	0
Fastening systems	1	Inconel 600	0	0
Cables	1	Copper Alloy	0	0

Credit: The data were obtained based on simulations using Debris Assessment Software (DAS)

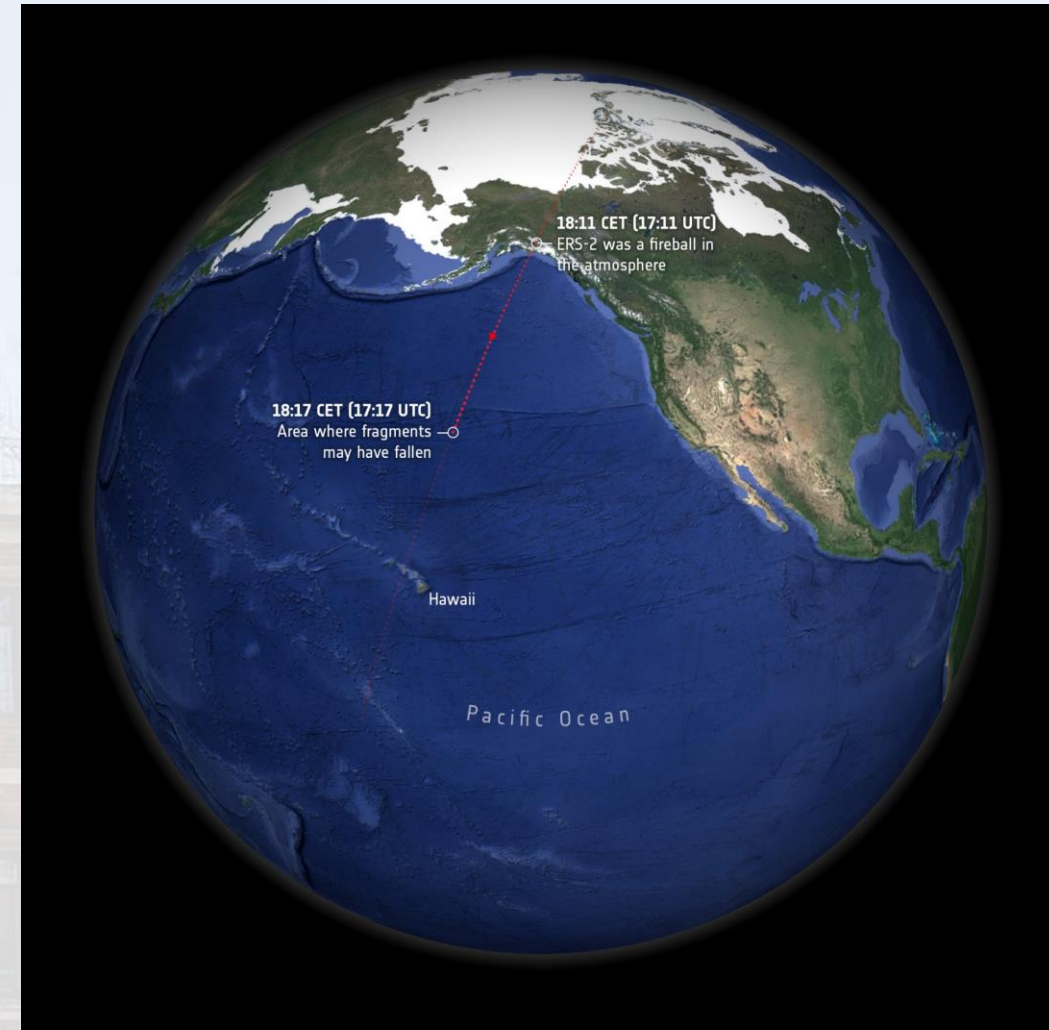
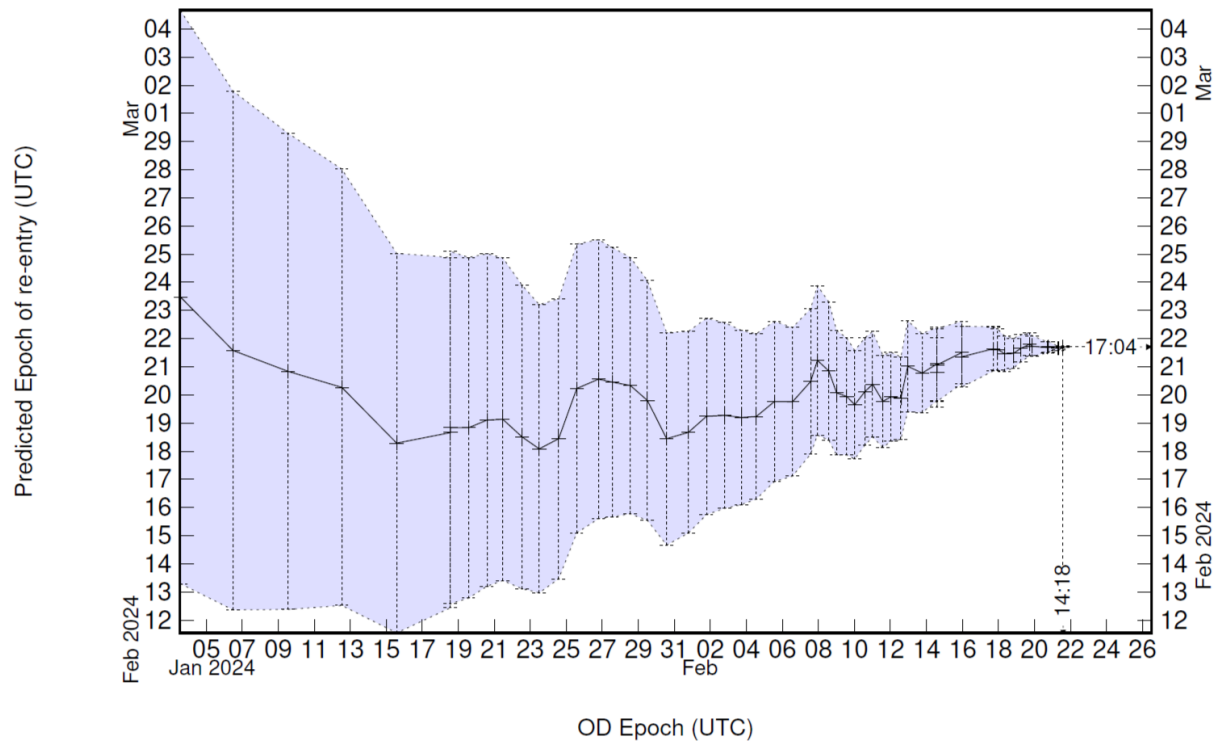
## II. Uncontrolled Reentry of the ERS-2 Satellite



- launched on 21 April 1995
- on 21 February 2024, it reentered the atmosphere in an uncontrolled manner, and the fragments were scattered over the North Pacific Ocean



ERS-2 (95021A,23560), TLEs till 24052.5965 (2024-02-21)  
 COIW: Central Time Of Impact Window (nom./-dt/+dt)  
 Last available orbit data (UTC): 2024/02/21 14:18:59.69  
 COIW (UTC): 2024/02/21 17:04:59.69, LON: -1.10, LAT: 70.47



# Reentry Simulations

a) Debris Assessment Software (DAS)  
developed by National Aeronautics and Space Administration (NASA)

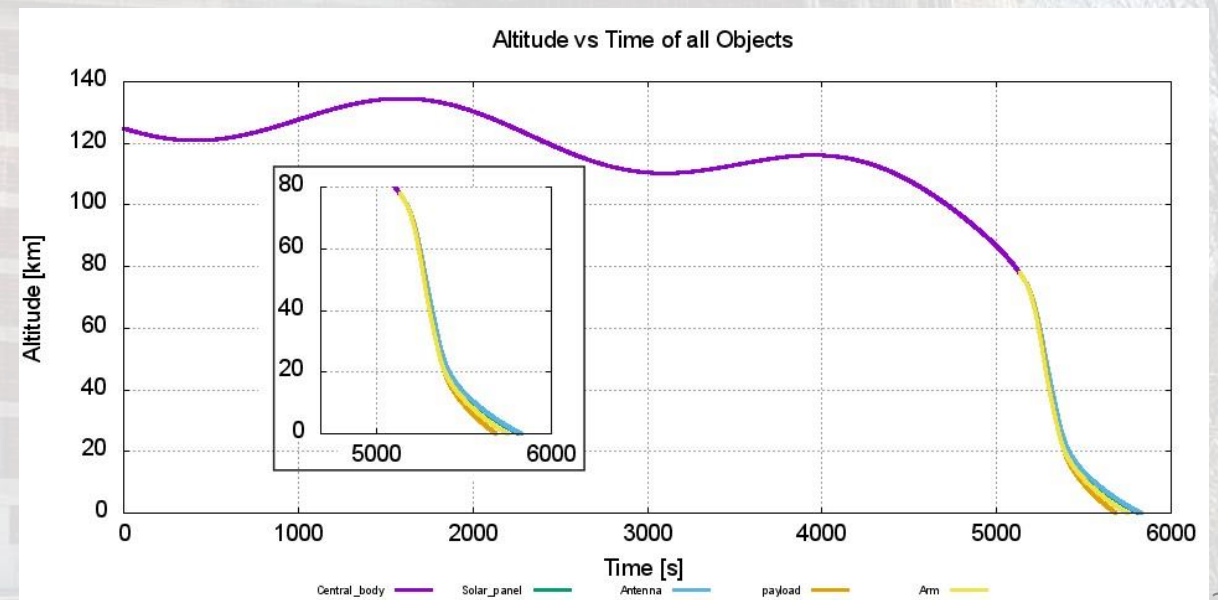
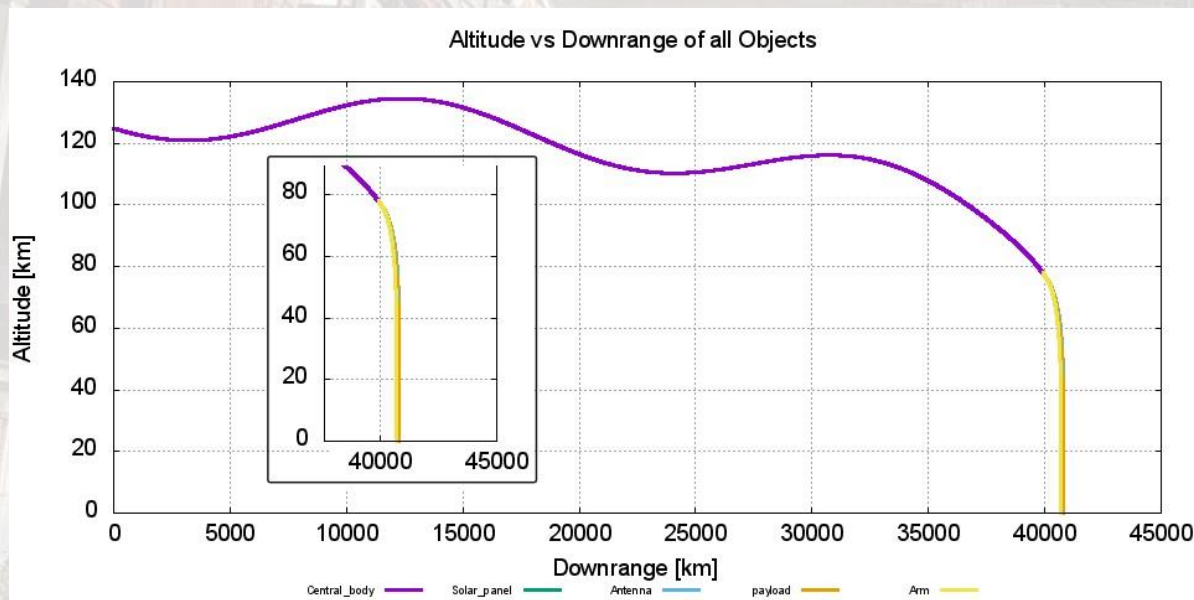
*Table 3*

Estimation of demise altitude and total DCA for the first scenario

Generic component	Number of items	Generic material	Demise Alt [km]	Total DCA [sq m]
Root Object	1	Aluminum (generic)	0	63.12
Central body	1	Aluminum (generic)	0	9.68
Antennas	1	Aluminum (generic)	0	14.67
Solar pannels	2	Fiberglass	0	38.76

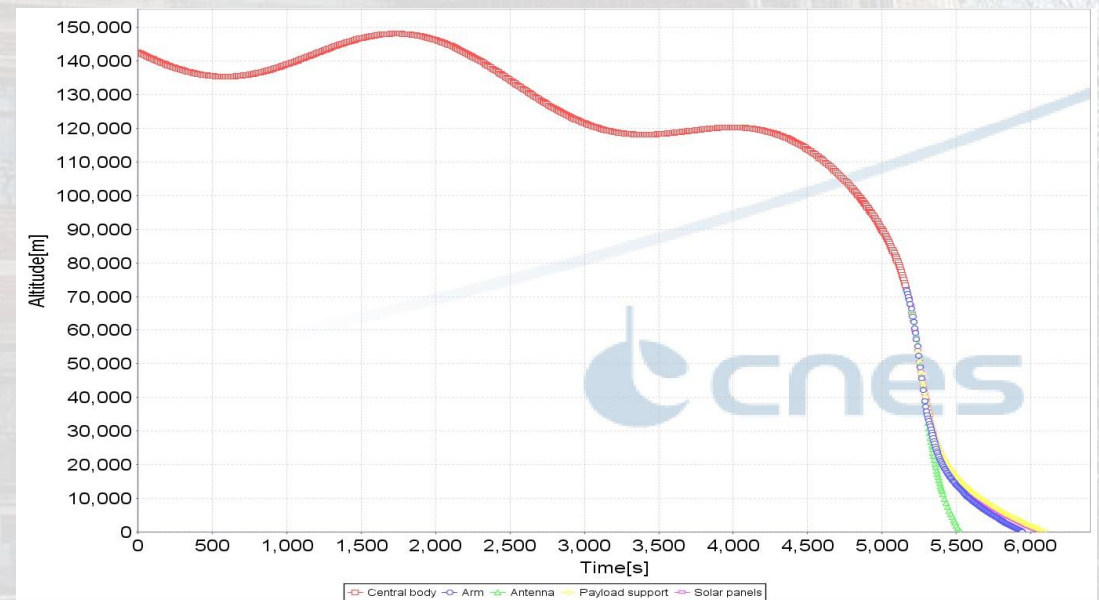
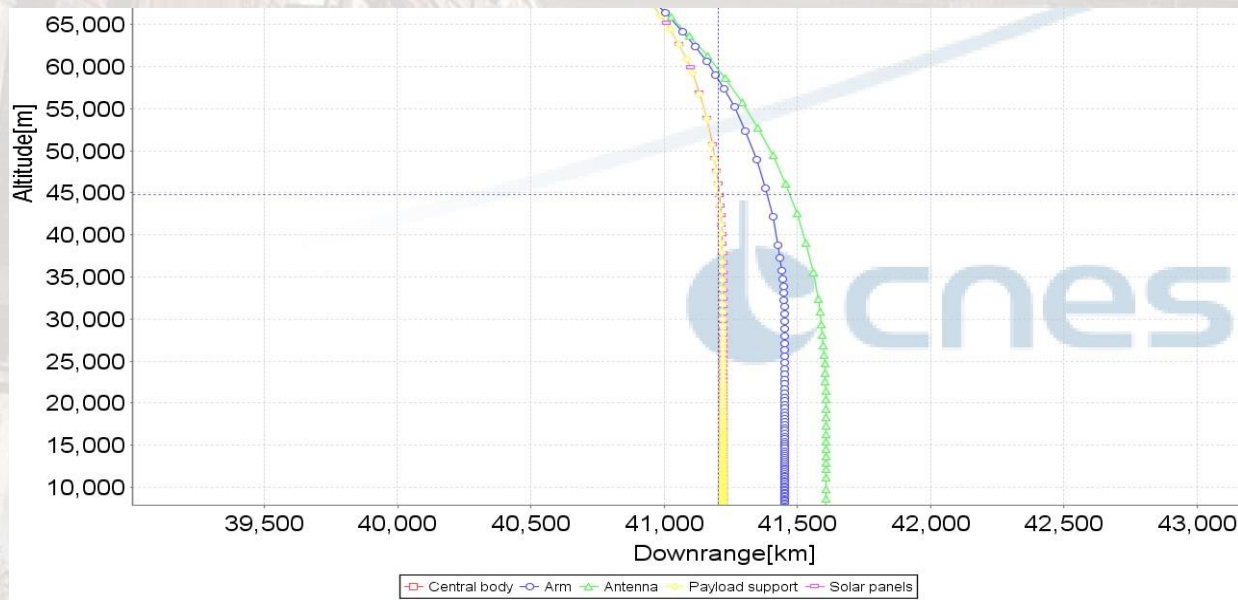
## b) Debris Risk Assessment and Mitigation Analysis (DRAMA) developed by European Space Agency (ESA)

- Input mode: Expert / Re-entry and Risk
- Re-entry type: uncontrolled
- Orbital states: the last TLE
- Satellite attitude: tumbling
- Environment dynamic NRLMSISE-00 with density scaling factor 1.0
- Solar flux 164 sfu (February 21, 2024) / Casualty threshold: 15 J

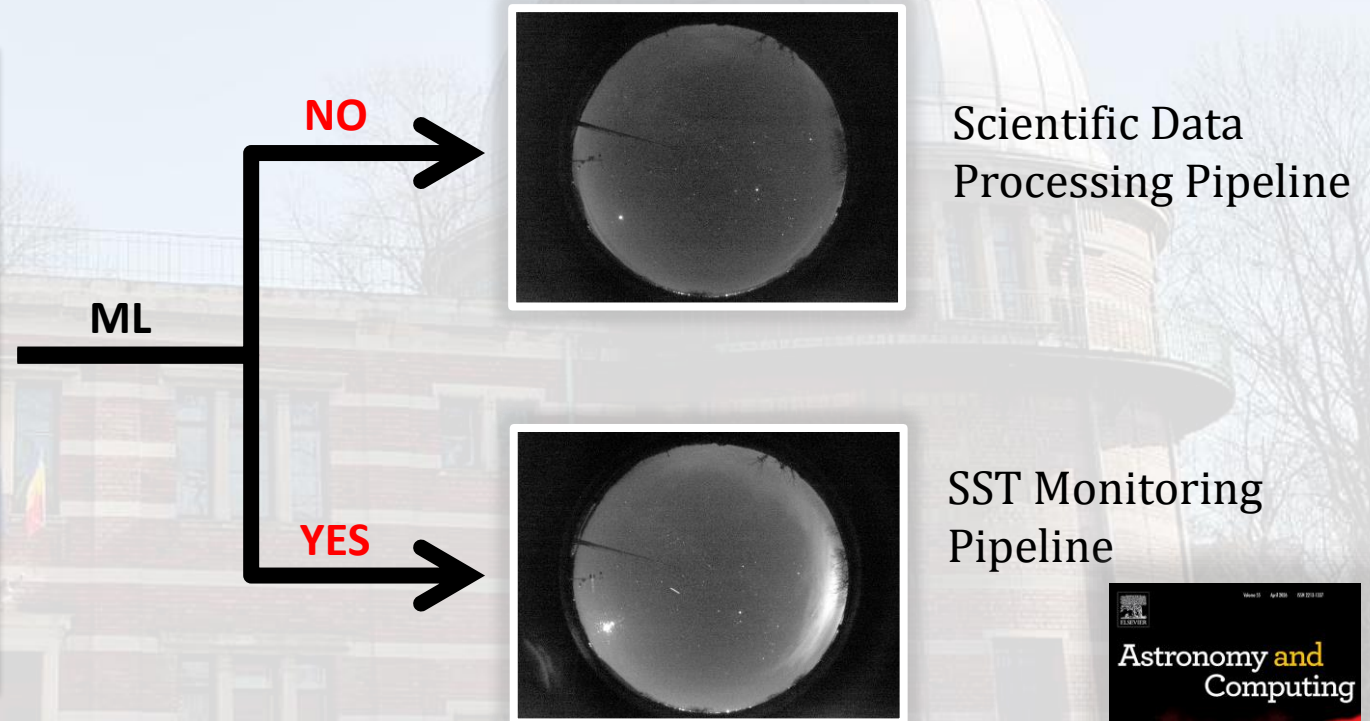
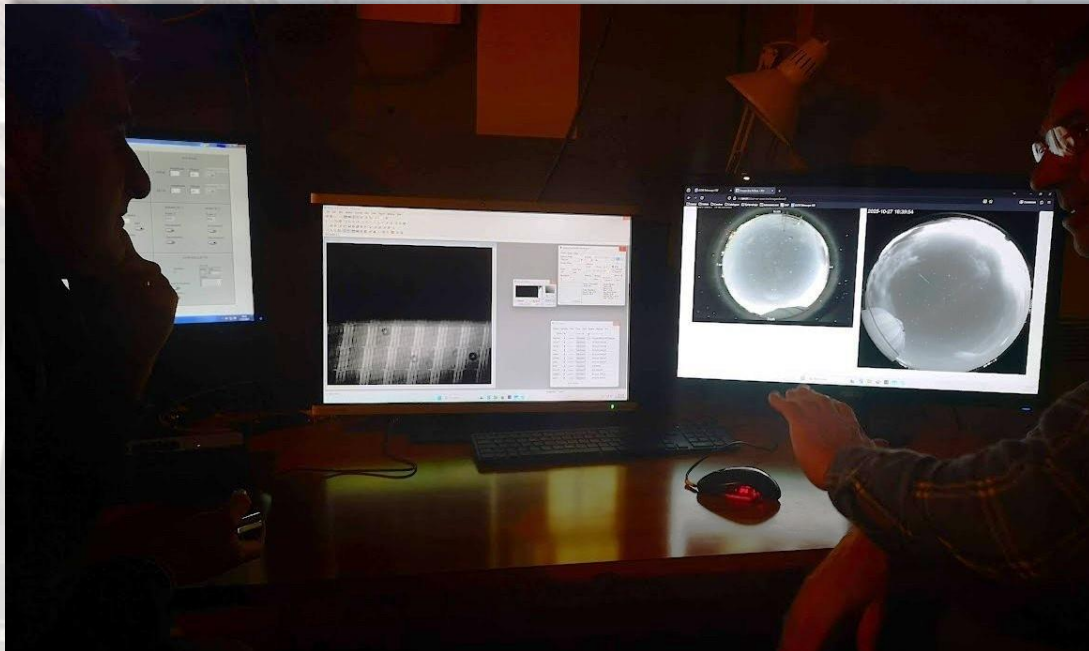


## c) DEBRISK developed by Centre National d'Études Spatiales (CNES)

- Input mode: Expert / Re-entry and Risk
- Re-entry type: uncontrolled
- Orbital states: the last TLE
- Satellite attitude: tumbling
- Environment dynamic NRLMSISE-00 with density scaling factor 1.0
- Solar flux 164 sfu (February 21, 2024) / Casualty threshold: 15 J



# Chapter 5: Impact on Observational Astronomy



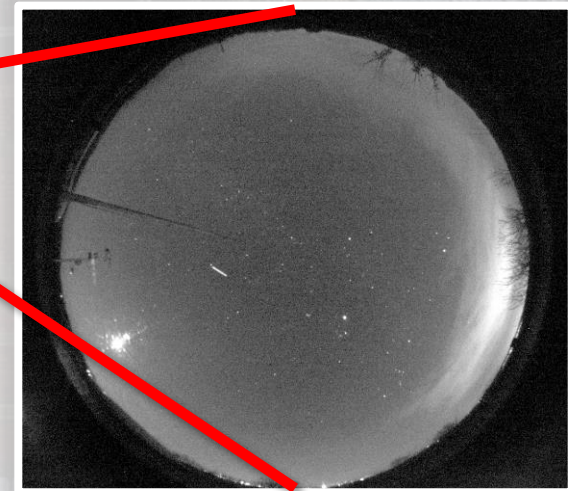
# Image Acquisition



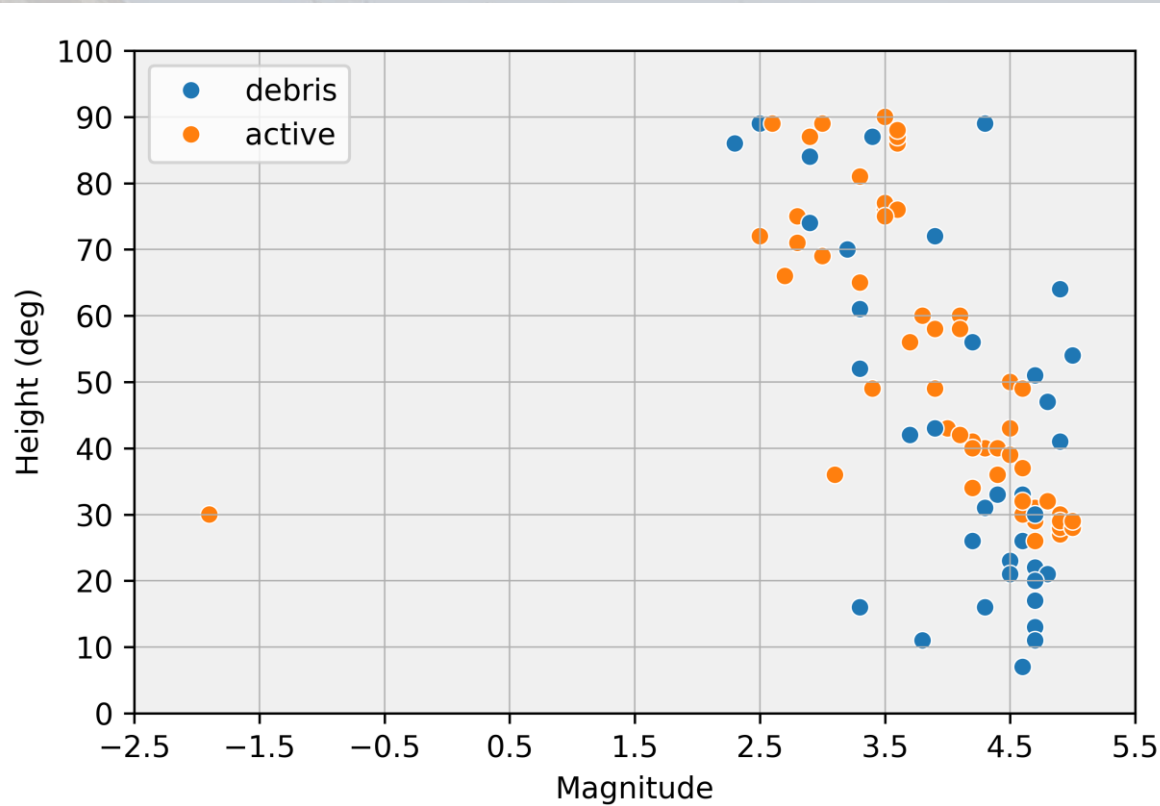
## Berthelot Observatory (IAU Code L54)

All-sky camera:

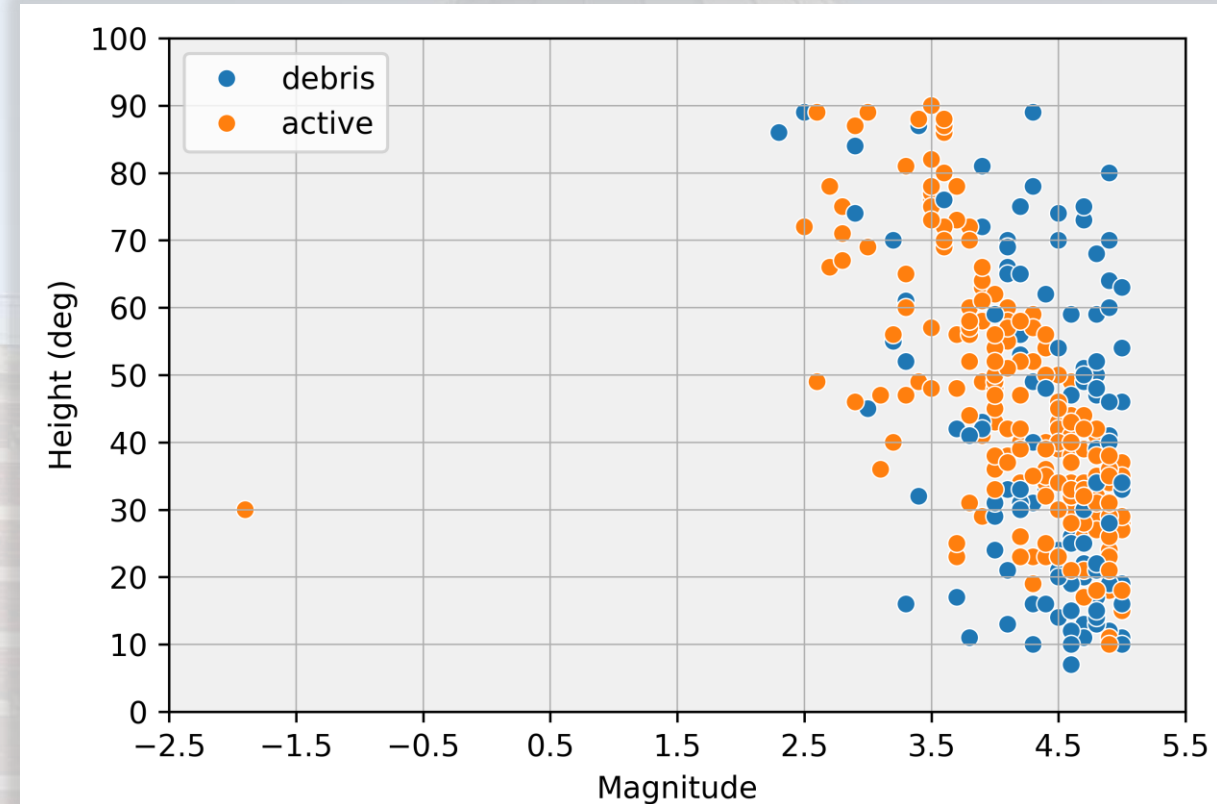
4.9 x 3.6 mm Sony CCD chip ICX445  
(1296 x 966 active pixels, 12 bit)



# Data Preprocessing

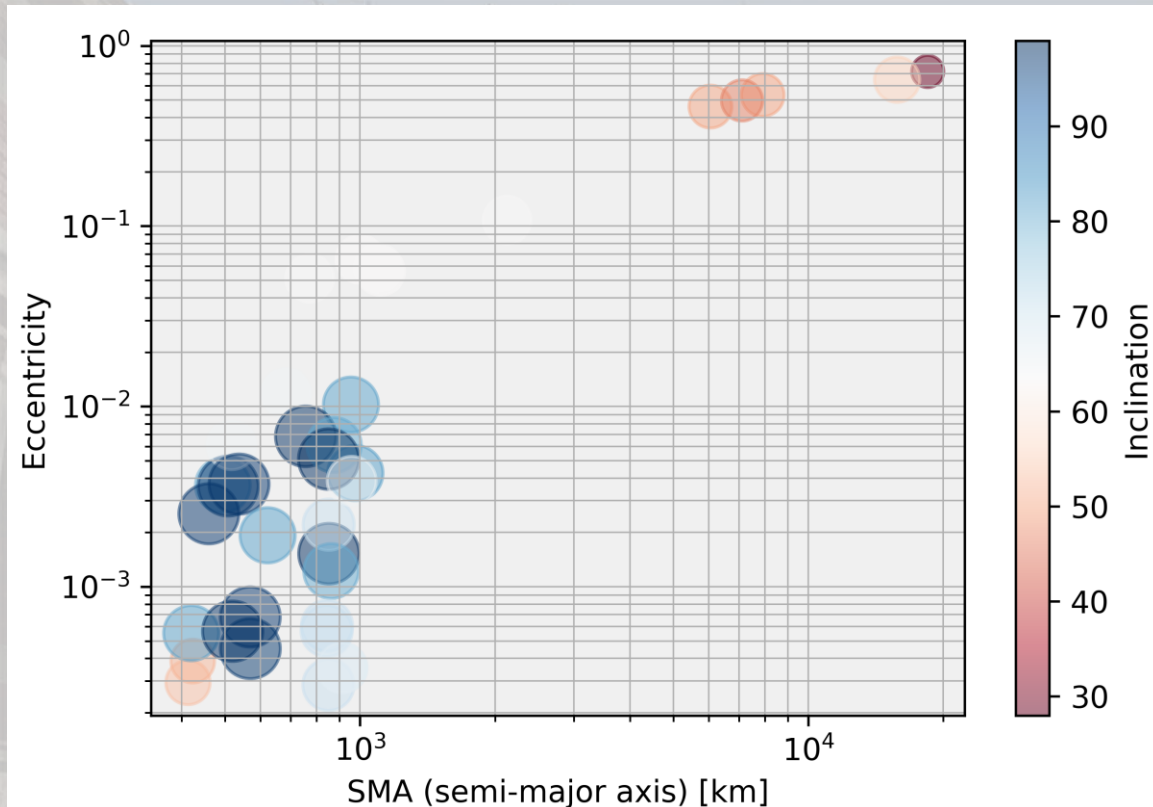


**Phase 1:** 1,589 FITS images acquired from 96 transits:  
59 satellites and 37 orbital debris objects

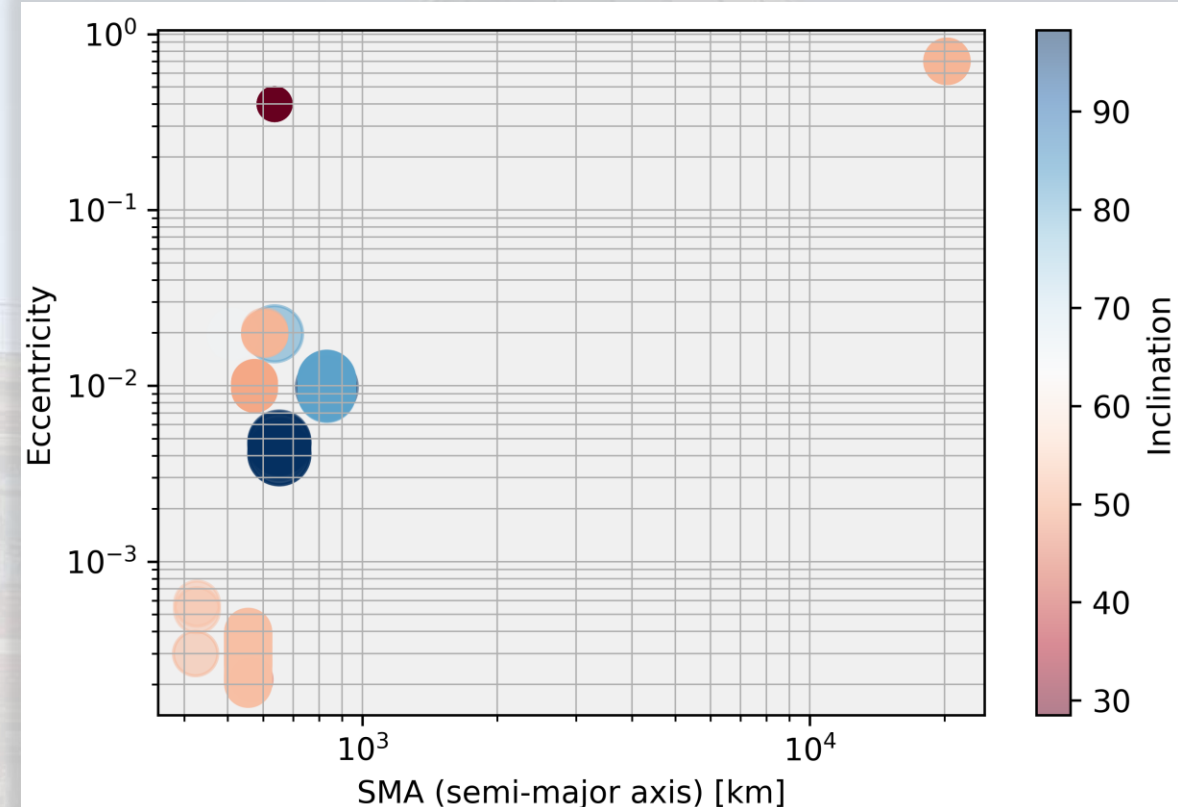


**Phase 2:** 8,596 FITS images acquired from 358 transits:  
224 satellites and 134 orbital debris objects

# Data Preprocessing

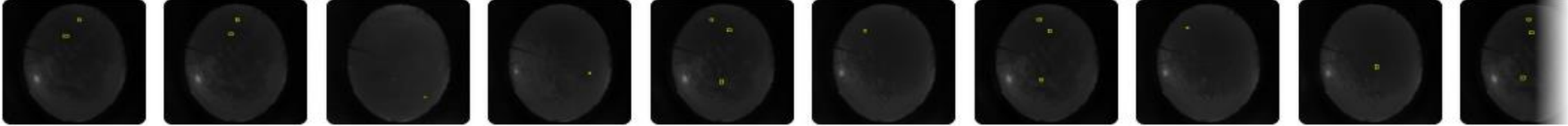


**Phase 1:** 1,589 FITS images acquired from 96 transits:  
59 satellites and 37 orbital debris objects



**Phase 2:** 8,596 FITS images acquired from 358 transits:  
224 satellites and 134 orbital debris objects

1411 Total Images [View All Images →](#)

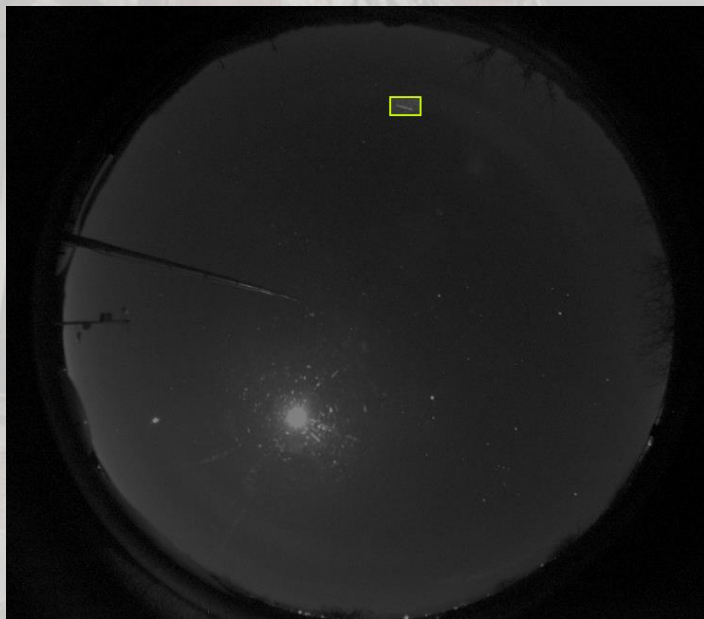


Dataset Split

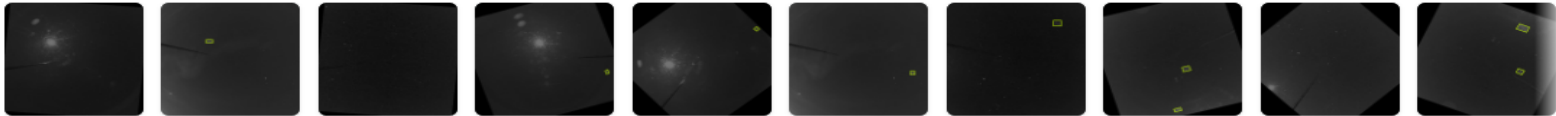
TRAIN SET	70%	VALID SET	20%	TEST SET	10%
988 Images		282 Images		141 Images	

← Phase 1

Phase 2  
↓



13162 Total Images [View All Images →](#)



Dataset Split

TRAIN SET	82%	VALID SET	11%	TEST SET	7%
10736 Images		1454 Images		972 Images	

Preprocessing

- Auto-Orient: Applied
- Resize: Fill (with center crop) in 640x640
- Grayscale: Applied

Augmentations

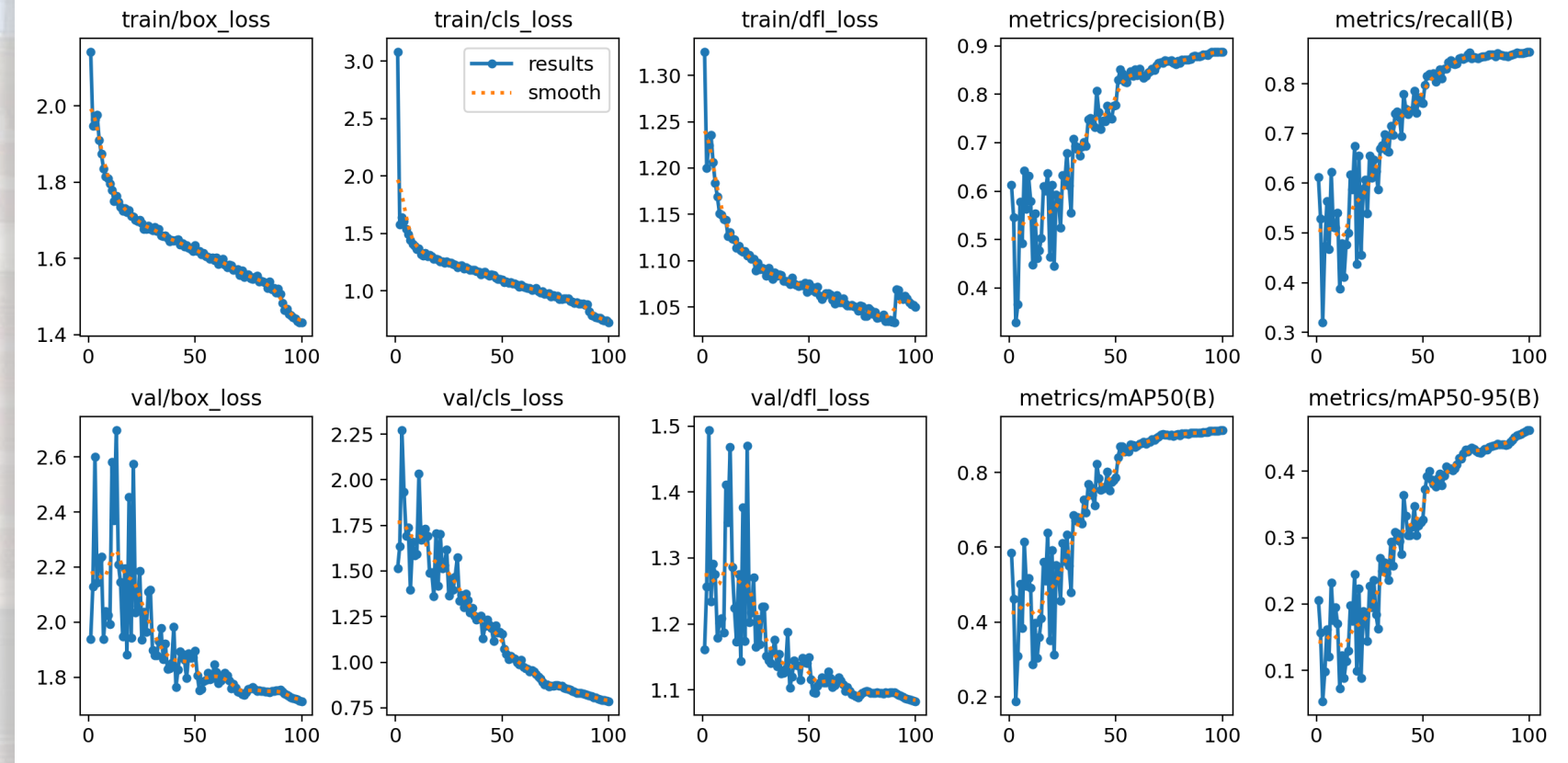
- Outputs per training example: 2
- Flip: Horizontal, Vertical
- Rotation: Between -45° and +45°

# Results

TP (True Positive) = 0,91  
 TN (True Negative) = 1  
 FP (False Positive) = 0  
 FN (False Negative) = 0,09

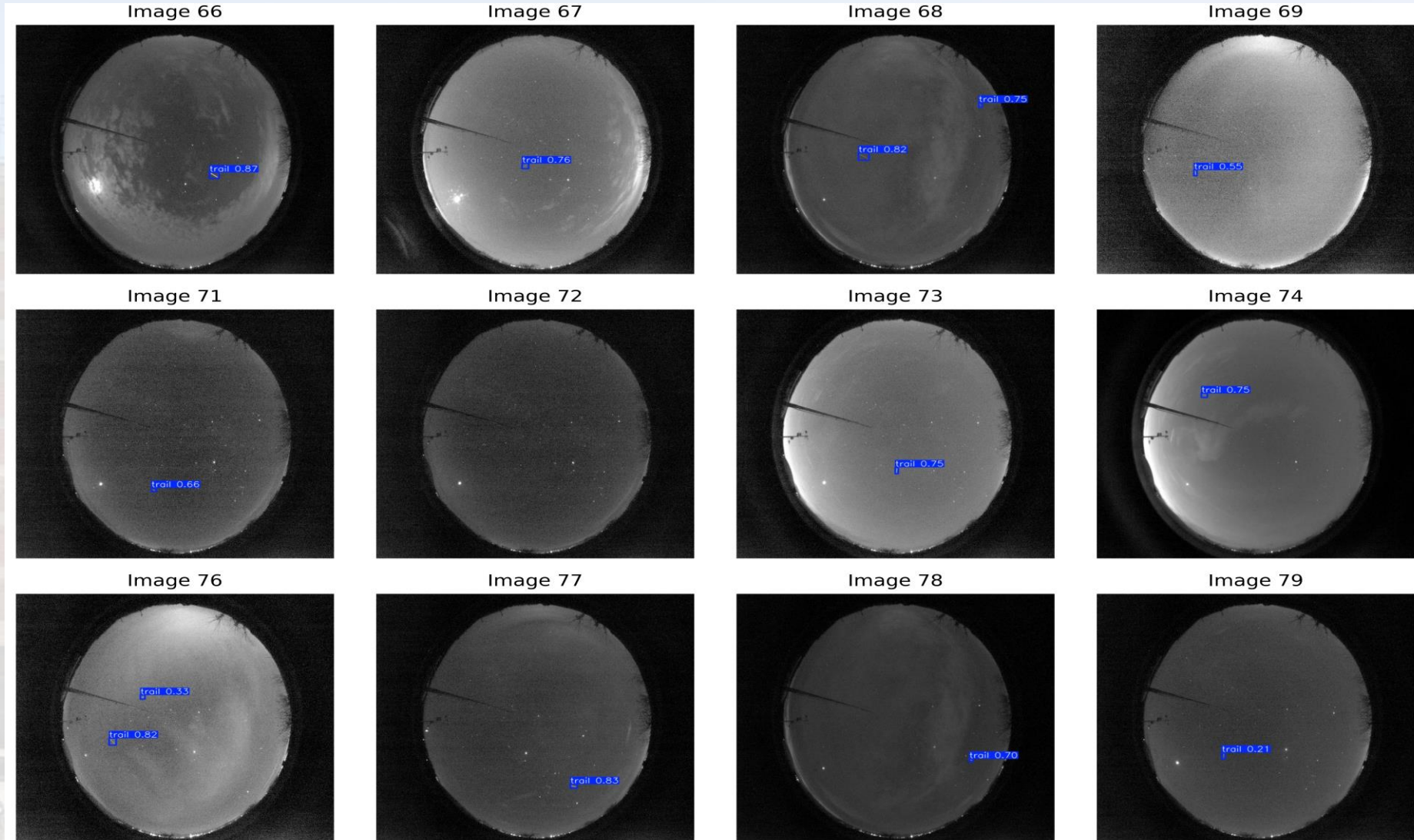
## Performance Metrics:

Accuracy = 95,5%  
 Precision = 100%  
 Recall = 91%  
 (only 9% of the trails  
 were missed)



# Predictions on the Test Set

- the system is not affected by clouds or light pollution
- multiple trails detected in images
- images with no trails detected



# Conclusions

## BALANCE IN INNOVATION

- launch cost optimization
- environmental factors and sustainability
- compliance with stricter technical regulations

## GLOBAL HARMONIZATION

- dynamic allocation of orbital slots and insertion licenses
- mandatory EOL deorbit plans
- common international standards

## LEGAL FRAMEWORK

- inadequate in the current context
- urgent revision of the *Outer Space Treaty*, ratified and in use since 1967

## ORBITAL DEBRIS REMOVAL

- ADR: experimentally demonstrated, not yet economically feasible
- Design for Demise (D4D): proactive solution, gradual adoption

# Original Contributions

## 1. Custom Space Object Detection Model

- deep learning architecture based on CNN, specifically trained for LEO object detection
- custom dataset: 8,596 original images → 13,162 images after augmentation

## 2. Development of a new component of the MOROI National All-Sky Camera System:

- integration of the solution for Space Situational Awareness (SSA) activities
- automatic frame sorting system for scientific purposes and Space Surveillance and Tracking (SST) monitoring

## 3. Atmospheric Reentry Analyses of Space Objects

- simulations using the following tools: DAS, DRAMA, and DEBRISK
- assessment of fragment survivability risk for controlled and uncontrolled reentries

## RE-ENTRY SURVIVABILITY ANALYSIS OF ERS-2 SATELLITE

CRISTIAN OMAT<sup>1,2</sup>, MIREL BIRLAN<sup>1,4</sup>, ALIN NEDELCU<sup>1</sup>, VLAD TURCU<sup>3</sup>, FLORENT DELEFLIE<sup>4</sup>, ULPIA ELENA BOTEZATU<sup>5</sup>

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<sup>3</sup>Cluj-Napoca Astronomical Observatory, 19 Ciresilor, Cluj-Napoca, 400487, Romania

<sup>4</sup>Laboratoire Temps-Espace, Observatoire de Paris, 77 av Denjers-Rochereau, 75014 Paris, France

<sup>5</sup>Romanian Space Agency, 21-25 D. I. Mendeleev street, Bucharest, Romania

**Abstract.** The history of the ERS-2 satellite is closely linked with that of its predecessor, ERS-1. The first one was launched on July 17, 1991, followed by ERS-2 on April 21, 1995. Both satellites significantly exceeded their original design life of three years, contributing extensively to various scientific and environmental applications during their operational periods. This study focuses on the ERS-2 satellite, whose mission officially ended on September 5, 2011. The final image from ERS-2 was received on July 4, 2011. Subsequently, after executing 66 deorbiting maneuvers, the satellite's altitude was reduced from 780 km to 573 km to facilitate natural orbital decay due to atmospheric drag. Approximately thirteen years later, on February 21, 2024, ERS-2 completed its atmospheric re-entry over the North Pacific Ocean, between Alaska and Hawaii, at the estimated coordinates 37°24'00.0" N and 151°54'00.0" W, at 18:17 CET (17:17 UTC).

The objective of this paper is to evaluate the risk of Earth impact by surviving fragments and to estimate the consequences of debris. Our analysis assumes that all satellite systems were disconnected, fuel purged, and the wind scatterometer failed. We use the model for re-entry simulation developed by the European Space Agency (ESA) in Bulletin of the European Space Agency (ESA) and the NASA-developed Debris Risk Assessment and Mitigation Analysis (DRA) software from the European Space Agency (ESA) and the French Space Agency (CNES).



Astronomy and Computing 55 (2026) 101001

Contents lists available at ScienceDirect

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Full length article

## Deep learning approach for automated detection of space objects in astronomical imaging

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### ARTICLE INFO

**Keywords:**  
Deep learning  
All-sky images  
Machine learning  
Satellite trail  
YOLO  
Image processing & techniques

### ABSTRACT

The exponential growth in low Earth orbit (LEO) satellite deployments over recent years has introduced substantial challenges for ground-based astronomical observations. Astronomers now routinely encounter satellite trails and space debris crossing their telescope fields of view, necessitating time-intensive manual inspection to identify usable frames for scientific analysis. Simultaneously, detecting and cataloging these objects is essential for building and maintaining Resident Space Object (RSO) catalogs, which support safe and sustainable space operations. This work develops and evaluates a deep learning approach based on YOLOv12 to automatically detect satellite and debris trails in all-sky astronomical images. We build a labeled dataset of 794 FITS images, derived from 8596 raw observations collected between January 24 and March 23, 2025 and expand it through augmentations for validation, and testing. Our trained models achieve high detection performance across different observational conditions, providing an efficient tool for identifying and supporting Space Situational Awareness through the discovery and monitoring of cataloged satellites within all-sky monitoring networks.

### 1. Introduction

All-sky cameras have become a familiar component of small and mid-scale observatories. They are routinely used for night sky monitoring, cloud coverage assessment, meteor/bolide detection, and public outreach. As a result, there is already a geographically distributed network of inexpensive, continuously operating, wide-field imagers producing long-exposure frames throughout the night. These systems were not originally built for satellite tracking, but they record exactly the kind of evidence, bright linear trails from artificial satellites in low-Earth orbit (LEO) and from larger debris fragments, that is becoming increasingly valuable for Space Surveillance and Tracking (SST). This is not an abstract concern. The number of active objects and

developed, including morphological models (Nedelcu et al., 2016) and neural-network-based systems (Nedelcu et al., 2024), these solutions are often designed for large telescopes or require significant computational resources, making them impractical for small all-sky camera networks. For many semi-professional distributed all-sky camera networks, fragmentation is often a constraint. For many semi-professional distributed all-sky camera networks, fragmentation is often a constraint. For many semi-professional distributed all-sky camera networks, fragmentation is often a constraint. For many semi-professional distributed all-sky camera networks, fragmentation is often a constraint.



## ANALYSIS OF THE RE-ENTRY PHASE OF STARLINK-1353 SATELLITE

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**Abstract.** Eighty-three percent of all operational satellites are debris. Starlink is the largest mega-constellation with 5,233 satellites in orbit available for June 2024 (Planet4589, 2023). To date, SpaceX has launched 6,505 Starlink satellites out of 11,908 units planned (with a total of 22,488 units). One of the failed satellites was the Starlink-1353, which the controlled decay above Hokkaido Island, on February 21, 2024, was observed by the field-of-view of one telescope from Kitauyabu Astronomy Club in a live streaming session (Kitauyabu, 2024). The video camera of the telescope and based on the analysis based on Debris Assessment Software (DAS) we identified 15 fragments resulted after the atmospheric re-entry, 64.4 km above the sea level and some fragments were observed in the field-of-view of one telescope from Kitauyabu Astronomy Club in a live streaming session (Kitauyabu, 2024). The video camera of the telescope and based on the analysis based on Debris Assessment Software (DAS) we identified 15 fragments resulted after the atmospheric re-entry, 64.4 km above the sea level and some fragments were observed in the field-of-view of one telescope from Kitauyabu Astronomy Club in a live streaming session (Kitauyabu, 2024). The video camera of the telescope and based on the analysis based on Debris Assessment Software (DAS) we identified 15 fragments resulted after the atmospheric re-entry, 64.4 km above the sea level and some fragments were observed in the field-of-view of one telescope from Kitauyabu Astronomy Club in a live streaming session (Kitauyabu, 2024).



### 1. INTRODUCTION

In recent years, the number of operational satellites in low Earth orbit (LEO) has increased significantly. The biggest increase has been in the number of satellites deployed. By 2024, approximately 100,000 satellites will be active in LEO, organized in some mega-constellations of satellites (Nedelcu et al., 2021). This unprecedented increase in LEO satellites brings many benefits for worldwide applications, but it also poses significant challenges for deploying satellites in low orbits has a significant impact on the environment and the safety of other satellites.

Nos. X, p. 1–17, Bucharest, 2024



## a. International conferences

*5th International Conference on Space Situational Awareness (ICSSA), Tres Cantos - Madrid, Spania, 7 - 9 aprilie 2026*

*9th European Conference on Space Debris, Bonn, Germania, 1 - 4 aprilie 2025*

*64th Israel Annual Conference on Aerospace Sciences (IACAS 2025), Haifa, Israel, 20 martie 2025*

*8th International Conference in Astronomy, Astrophysics, Space and Planetary Sciences, Cluj-Napoca, 2 - 4 iulie 2025*

*3ème Édition du Symposium de la Recherche Scientifique Francophone en Europe Centrale et Orientale, Cluj-Napoca, 16 - 17 decembrie*

*6th International Workshop on Key Topics in Orbit Propagation Applied to Space Situational Awareness (KePASSA), Arras, Franța, 12 - 14 iunie 2024*

## b. National conferences

*Conferința Cercetării Științifice în domeniul Matematicii dedicată împlinirii a 160 de ani de la înființarea Academiei Române, Institutul de Matematică "Simion Stoilow", Academia Română, București, 30 - 31 martie 2026*

*Doctoral Dialogues in Physics 2025, Facultatea de Fizică, Universitatea din București, 10 - 11 octombrie 2025*

*Bucharest University Faculty of Physics 2025 Meeting, Facultatea de Fizică, Universitatea din București, 23 mai 2025*

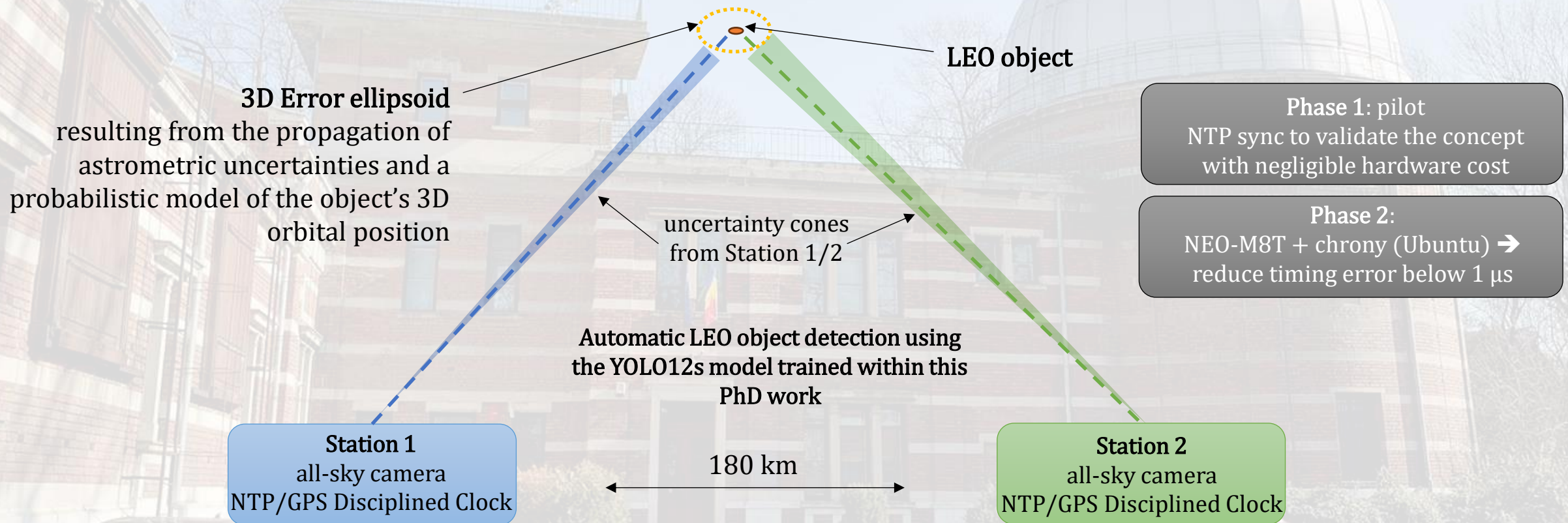
*Bucharest University Faculty of Physics 2024 Meeting, Facultatea de Fizică, Universitatea din București, 24 mai 2024*

*Modern Techniques in Observational Astronomy, comuna General Berthelot, județul Hunedoara, 1-5 iulie 2024.*

*Bucharest University Faculty of Physics 2023 Meeting, Facultatea de Fizică, Universitatea din București, 26 mai 2023*

# Future Work and Perspectives

## Probabilistic 3D Position Reconstruction of LEO Objects via Dual-Station Triangulation for Space Situational Awareness (SSA)



# Thank you!

I would greatly appreciate your feedback

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